Brief Description

- Stage Controller for Compressor Compounds, Brine-
- Chillers and Condenser Fans 4 stages, by adding "Slave"-device
- up to 8 stages possible For Single- and Multi-Stage
- Loads
- Automatic Stage Sequencing Autoadaptive Trend Recognition
- Inputs for 2-wire Pressure Transmitters, Pressostat and Temperature Probes
- Analogue Output 0-10V DC for
- Motordrives or Remote Displays 2nd Setpoint by internal clock
- Peak Load Limitation / Fast Back-
- run / Emergency Operation Compressor Idle Time
- Integrated operation time counters RS-485-Interface ٠

Applications



ELEKTRONISCHE REGELUNGEN GMBH

Technical Manual

5311032-05/11E from Software Vers. 1.9.2

Stage Controller for Compressors, **Condenser Fans or Brine Chillers** Series





Technical Data

Supply Voltage	see above
Output Relays	
Contact Rating	8A resistive, 3A cos phi 0,4, 250V AC
MSR 1100-Ž / S (UL)	resistive: 120/240V AC, 8A, 30 k cycles
	motor: 125/250V AC, 1/4 HP, 30 k cycles
Ambient Temperature MSR 1100-2/	S10+65°C (14149°F)
Ambient Temperature MSR 3100-2/	5100-2 -10 +55°C (14 131°F)
Storage Temperature	-30 +70°C (-22 158°F)
Relative Humidity	max 85% r H not condensing
Signal Input	2x TE 201 or 2x TE 501
1v	4 20 m (Ri= 100 Obm) Pressonation
Supply Voltage for 2 wire process	transmittor
Supply vollage for 2-wire pressure	appr 24V/DC uprog may 22 mA
MCD 1100 0 DC	appl. 24V DC, unleg., max. 23 mA
MSR 1100-2DC, uni	eg., dep. on transformer, max. 23 mA
Display LED, 7-segmen	t, red, character height 13mm (.51 inch)
Resolution	
Control-/Display Range	see parameter listing
Data Storage Parameters	≥20 years
Clock Backup	typ. 10 days after mains is lost
Relay Indicators	3 mm, red
Analog Output	0-10 V DC, max. 3 mA
Analog Output Resolution	
Data Interface	E-Link (RS-485)
Electrical Connection	screw terminals 2,5mm ²
Housing / Protection / Digital Input	
MSR 1100-27	7 x 35 mm front frame, IP 54 from front
Digital	input for external, potential free contact
MSR 1100-2 S	7 x 35 mm front frame. IP 54 from front
Digital	input for external, potential free contact
MSR 3100-2	for rail mounting JP 30
Digital input	for mains voltage 50-60Hz max 3mA
MSR 5100-2	6 x 48 mm front frame IP 54 from front
Digital input	for mains voltage 50-60Hz max 3mA
	Tor maine voltage, 50-001 z, max. SmA
Further data you will find on the pa	rameter listing.
Accessories (plazes order separ	atoly)

- 2-wire pressure transmitter, Type DG 0/10 GSW, with 4-20 mA output 2-wire pressure transmitter, Typ DG 0/25 GSW, with 4-20 mA output 2x temperature sensors TF 201 (PTC) or TF 501 (Pt1000)

- For type MSR 1100-2: Transformer 107-1300-0052 (220/ 12V / 5VA) or Transformer 107-1300-0018 (22V / 5VA)

Please read these instructions carefully before applying power. Your attention is drawn to the fact that the warranty is subject to the application of power sources that are within the limits specified in this manual. This documentation was compiled with utmost care, however, we cannot guarantee for its correctnesss in every respect. Technical details can be changed without notice, especially the software. Please note that the described functions are only valid for units containing the software with the version-number shown on page 1. Units with an other software number can work a little bit different. You will find this software number on the label of the unit too.

ELREHA GmbH

D-68766 Hockenheim, Germany, Schwetzinger Str. 103

 Refrigeration, Heating and Air Conditioning Technologies

Different terminal assignment, 8 stages by 'slave' module Error messages now as codes + error listing Notice Unlock code entry now possible at each parameter - 4 new parameters, new codeparameter is (P58) **Operating Elements** On/Off: Stage 1 Stage 2 Stage 3 Stage 4/Alarm Automatic segment test after power-up !! increase values programming negative sign Ρ key decrease MSR ELREH/ values

Changes of the -2 types in comparison to the older ones

Parameters

All selectable parameters hold a parameter number (e.g. P03), you will find a listing on the next page.

blinking: night setpoint

All MSR-versions are marked in the same way

blinking:

data transmission

Calling up and editing

canning up and canting	
Press key 'P'	.parameter number appears
Use 'û/	select desired parameter (hold key for autoscroll)
Press "P" again	.parameter value appears
Use keys 'û/↓'	adjust parameter value (hold key for autoscroll)
Press 'P' again	.value is stored, back to parameter no.

Unlock Keys / Access code

To prevent un-authorized persons from editing parameter values, there is a locking function which allows only the most important parameters to be changed at any time. All other parameters must be unlocked as follows:

enter access code before programming at parameter P58 directly at the parameter to be changed. If a code no. is necessary the display shows "C00". Set the matching code no. by the "û/ℚ"-keys (70 or 80, see parameter listing) and confirm by "P". If no key is hit for about four minutes, the access code is cancelled and the

editing function is locked automatically. After entering code "70" (basic configurations), a fast backrun will be initated. The control sequences restart first after the code is changed

manually (e.g. to 88) or is reset after 4 minutes automatically.

Start-up behavior

Directly after start-up the display shows a controller type number, after that a display test passes.

How to find out the current operation mode Hold key "P" for > 2 sec. = Display shows the for

old key "P" for > 2 sec. = Display shows the following values: 106 = operation mode for compressors/compounds

- 206 = operation mode for condenser fans
- 300 = operation mode for chiller sets

Setting the operation modes (see examples on the last page)

- Switch controller off
- Hold key "P", switch controller on and wait until "___" appears on the display
- Release key "P"
- Release Rey F Select desired configuration by "û" "1 ___ = for compressors (pressure controlled) "2 ___ = for condenser fans (pressure controlled) "3 ___ = for chillers (temperature controlled)
- Press "P" once to confirm
- Display shows "def", all default values are loaded
- The actual value appears, ready for start-up.



Please note Safety Instructions! While replacing older types please note changed functions!

Param	Parameter Listing								
Para. No.	ra. Oper. Code Mode		Code	Description	Factory	Settings		Ranges	
	Compress. Fans	Br. Chillers	1 Notice	 X = Parameters visible depending on operation mode * = not available if a pressostat is used Code 70 = control functions first starts if access code is reset (see 'operating') cnbe = cannot be edited by the user 	Compress.	Fans	Br. Chillers		
P01 P02 P03 P04* . P05 P06 P07 P08				Actual value control sensor (water inlet) or pressure transmitter Actual value of limitation sensor (water outlet) Status of forward / backward / peak load limitation Setpoint 1 (absolute, start of backrun) Setpoint 2 (relative resp. switching distance to P04) Setpoint 3 (relative resp. switching distance to P05) Setpoint 4 (relative resp. switching distance to P06) Setpoint 5 (relative resp. switching distance to P07) Setpoint 5 (relative resp. switching distance to P07)	 	- - - 0 0 0 0 	 0 0 0 0	within the limits P12/P13 010.0 010.0 010.0 010.0 010.0	
P10 P11 P12* . P13* . P14* . P15				Setpoint 7 (relative resp. switching distance to P09) Setpoint 8 (relative resp. switching distance to P09) Setpoint 8 (relative resp. switching distance to P10) Highest adjustable setpoint (for P04) Lowest adjustable setpoint (for P04) Hysteresis / Neutral Zone Limitation Value. Below this value all stages will switch off with their fixed backrun delay	+30.0 1.0. 	.0 .0 .+30.0 1.0 .2	0 	.010.0 010.0 100.0+100.0 100.0P12 0.510.0 100.0+100.0	
P16 P17* . P18* .	×	x (x	88 88 88	Hysteresis of Limitation Value P15. Upper Alarm Limit (relative to P04/P44). If exceeded and after delay P19 the alarm relay will be activated (if available) Lower Alarm Limit. Below this limit all stages will switch off in 1 sec. staps	+31.0	+31.0 1.0	+100.0 100.0		
P19* P20 P21 P22 P23 P24 P25 P26 P27 P28 P29 P30			88 70 70 70 70 70 70 70 70 70 70 88 88 88 88 88	Alarm Time, an alges vin selection in resc. steps, after delay P19 the alarm relay will be activated (if available) Alarm Time Delay Power Stages of compressor resp. fan 1 Power Stages of compressor resp. fan 3 Power Stages of compressor resp. fan 4 Power Stages of compressor resp. fan 5 Power Stages of compressor resp. fan 6 Power Stages of compressor resp. fan 6 Power Stages of compressor resp. fan 7 Power Stages of compressor resp. fan 7 Power Stages of compressor resp. fan 7 Power Stages of compressor resp. fan 8 Power Stages of compressor resp. fan 9 Power Stages of compressor resp. fan 9 Po	0 1 0 0 0 0 0 0 0 0 0 10 10	0 0 0 0 0 0 0 10 10 10 0 10	0 .0	060 min 14 .03 .03 .03 .03 .03 .03 .03 .03 .03 .03 .0600 sec .0600 sec .0600 sec	
P31 P32 P33	X.X	(X	70 88	. Switching Mode Relays K1, K4 and K8 (a) = active on, i.e. relay switches on (p) = passive (active off), i.e. relay switches off .Number of remaining stages after peak load limitation Base Load Change (Stage Sequencing)		0	2	0=K1(a), K4(a), K8(a) 1=K1(p), K4(a), K8(a) 2=K1(a), K4(p), K8(a) 3=K1(p), K4(p), K8(a) 4=K1(a), K4(a), K8(p) 5=K1(p), K4(a), K8(p) 6=K1(a), K4(p), K8(p) 08 0=off 1=on	
P34 P35	X.X	(X	88 88	Operating mode of Digital Input DI/OK 1 Operating mode of Digital Input DI/OK 2 Not available in MSR 1100-2, must be set to "0"	0		0	. 0=off, 1=night setpoint 2=peak load lim. 3=fast backr. . 0=off, 1=night setpoint 2=peak load limitation	
P36	.xx	(X	10	.Master-/Slave Mode			1	 3-1 additional slave unit, K4 is alarm relay, no network 1= standard, max. 4 stages, networking possible 2= additional slave unit, K8 is alarm relay, networking is not possible 	
P37 P38* . P39* . P40* . P41* . P42 P43* .				Calibration of control sensor or pressure transmitter Calibration of limitation sensor Upper pressure value the transmitter delivers 20 mA Lower pressure value the transmitter delivers 4 mA Remaining Time forward/backrun delay Remaining Time until an alarm will be activated.		.4 0 .30.0 -1.0 -	1 0 	4 = 420 mA, 5=Pressostat 10.0+10.0 1.0+10.0 1.0+100.0 1.0+100.0 1.0P40	
P44* . P45* . P46* . P47* . P48* . P49 P50 P51	X X X X X X X X X X X X X X X X		88 88 88 88 88 88 88 88 88 88 88 88 88	Night Setpoint / 2nd Setpoint (replaces P04) ON-time of Night / 2nd Setpoint (hours) ON-time of Night / 2nd Setpoint (minutes) OFF-time of Night / 2nd Setpoint (hours) OFF-time of Night / 2nd Setpoint (minutes) Actual Value the analog output delivers 10V * .Actual Value the analog output delivers 0V * .Mode of the analog output	0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0	100.0+100.0 023 h 059 min 059 min 100.0+100.0 100.0P49 0= off, 1= proportional,	
P52 P53 P54 P55		(.X (.X (.X	 	Clock Time 'hours' Clock Time 'minutes' Clock Time 'seconds' Data Transmission Speed (Baudrate)	 4	 . 4	 4	2= anti-proportional 023h 059 min. 59 sec. 1 = 1200, 2 = 2400, 3 = 4800 4 = 9600, 5 = 19200, 6 = 28800, 7 = 57600	
P56 P57 P58 r 01 up to r 08		(.X (.X (.X (.X	88 cnbe cnbe	Address of the controller unit in a network Current Error + Error Listing Access Code Operation Time Counter for relay K1 (hours = display x 10) Operation Time Counter for relay K8 (hours = display x 10)	78 multiple 00 0		I78 esent: scrol 0 0	178 I by up/down keys 099 9999 hours 9999 hours	

Operation Mode Indication

The parameter P03 indicates the current operating state of the controller. If a 'pressostat' is selected as input source, P03 is the standard indicator.

The following information is possible:

Unit is in 'forward' mode

Unit is in a state of stability, no stages will switch off or on

Unit is in 'backrun' mode

Limitation in progress

Night / 2nd Setpoint active

Fast Backrun

Peak load Limitation active

Minimum Idle Time still running

Failure Handling

Sensor short circuit or broken If one of the sensors is broken, disconnected or hot-wired, or the value is located outside of its specified range, the display shows "- - -" at first. After 1 minute the display flashes and shows an error code, at the same time the alarm relay K4 will be activated (if available).

Error Codes

E00	no failure
E01	sensor F1 broken
E02	sensor F1 hot wired
E03	sensor F1 overtemperature
E04	sensor F1 low temperature
E05	sensor F2 broken
E06	sensor F2 short circuit
E07	sensor F2 overtemperature
E08	sensor F2 low temperature
E09	digital input 1 failure
E10	digital input 2 failure
E11	4-20mA input broken (I < 3 mA)
E12	
E13	
E14	
E17	assignment error (to many stages selected)
E18	

Functional Description

Selection of Operating Mode The MSR can be configured for controlling compressor compounds, for condenser fans and brine chiller systems. While this configuration, all adjusted para-meters will be **erased** and replaced by suggestive default values. Not necessary parameters will be suppressed (see start-up examples).

Operation Mode 1 (compressor compounds)	Operation Mode 2 (condenser fans)	Operation Mode 3 (Brine-Chillers)						
<u>Input signals of the controller</u> The input signal comes from a 2-wire pressure transmitter with a 4-20 mA-signal or a pressostat, selectable by parameter P37 .	Input signals of the controller The input signal comes from a 2-wire pressure transmitter with a 4-20 mA-signal or a pressostat, selectable by parameter P37 .	Input signals of the controller 2 Temperature Sensors TF 201 or TF 501, selected by P37 . The control sensor should be mounted at water reflux (brine backflow, chiller inlet). The second						
Actual Value and Status Display P01 shows the pressure value of the transmitter. If the controller is configured for working with a pressostat, P03 becomes the standard display. P03 is a status display, which shows states like Forward/Backrun, Neutral State and others (see 'Operating'). From every state, 4 minutes after the last keypress the display switches back to the actual value. <u>Calibration of Transmitter and Actual Value</u> A pressure transmitter delivers its value by a 4-20 mA-signal. With P40/P41 you select the pressure values which are shown and processed with 4 or 20 mA input current. With P38 the actual value display (P01) can be adjusted. <u>Probe Failures</u> If a transmitter malfunction is identified, all stages will switch ON with the selected delay. After the alarm delay P19 is run down, the alarm relay K4 switches (if available). <u>Limit values</u> If the pressure value falls short of the limitation value P18 , all running stages will be de-activated in 1 se- cond steps. After the alarm delay P19 is run down, the alarm relay (K4) switches if available.	Actual Value and Status Display P01 shows the pressure value of the transmitter. If the controller is configured for working with a pressostat, P03 becomes the standard display. P03 is a status display, which shows states like Forward/Backrun, Neutral State and others (see 'Operating'). From every state, 4 minutes after the last keypress the display switches back to the actual value. <u>Calibration of Transmitter and Actual Value</u> A pressure transmitter delivers its value by a 4-20 mA-signal. With P40/P41 you select the pressure values which are shown and processed with 4 or 20 mA-signal. With P40/P41 you select the pressure values which are shown and processed with 4 or 20 mAinput current. With P38 the actual value display (P01) can be adjusted. <u>Probe Failures</u> If a transmitter malfunction is identified, all stages will switch ON with the selected delay. After the alarm delay P19 is run down, the alarm relay K4 switches (if available). <u>Limit values</u> If the pressure value exceeds the limitation value P17 (which is relative to the setpoint) and the alarm delay P19 is run down, the alarm relay (K4) switches if available.	sensor measures the temperature limitation value at the chiller's outlet. Actual Value and Status Display P01 shows the inlet temperature, P02 the outlet temperature. P03 is a status display for Foreward/ Backrun, Neutral State and others. From every state, 4 minutes after the last keypress the display switches back to the actual value. Calibration of Sensors and Actual Value Correct the temperature displays by P38 and P39. Probe Failures If a probe malfunction is identified, all stages will switch OFF with their backrun delay. After the alarm delay P19 is run down, the alarm relay K4 switches (if available). Limit Values Temperature Limitation If the outlet temperature at sensor 2 falls short of P15, a regular backrun will be initiated and all stages will switch off after their delay (P29). P16 is the hysteresis value for P15. Frost Protection If the inlet temperature falls short of P18, stages will switch off in 1 second steps. After the delay P19 the alarm relay K4 switches (if available). Temperature Alarm If the inlet temperature exceeds P17, the alarm relay K4 switches after the alarm delay P19.						
All Operating Modes P43 always show the remaining time of a running alarm delay. <u>2nd Control Setpoint 1 / 'night'-shift</u> Sometimes it is desired to shift the setpoints e.g. to spare energy at night. With P44 a 2nd setpoint 1 will be fixed and can be activated by the internal time-switch or the digital inputs DI/OK1 and DI/OK2. Within the times set by P45 and P48 the second setpoint is active. If not necessary, the times can be set to "0". Please note that initiation by digital(OK)-input has more priority as the internal clock.								
Stage Controller The control characteristic of the stages differ depending on the <i>operating mode</i> and the <i>selected sensors</i> . To prevent the final user from adjusting the setpoints to an inadmissible value, the setpoint range can be limited by P12 and P13.								
Stage Controller + Pressure Transmitter (Compressors) The control setpoint is preset by P04 as a pressure value, no access code necessary. The hysteresis P14 is located symmetrical around the control Stage Controller + Pressostat (Compressors or Fans) The MSR gets the Forward/Backrun information from a Pressostat (or another potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact). Functions depending on analog signals are nother potential free contact.								

setpoint.

Forward (Stages on) If the measured pressure value exceeds the setpoint (P04 + 1/2 P14 (hysteresis), the forward delay P28 starts. After this timer is run down, a stage will be switched ON and the timer starts again. Read at P42 if a delay time is still running and when a stage will be switched on or off.

 $\frac{Neutral \ zone}{If \ the \ actual \ pressure \ value \ is \ located \ within \ the \ hysteresis \ \textbf{P14} \ (located$ around the setpoint), no stage will be activated or de-activated.

Backrun (Stages will switch off)

If the actual pressure value falls short of P04 - 1/2 P14, the backrun delay P29 starts. After this timer is run down, one stage will switch off, the timer starts again, and so on.

Stage Controller + Pressure Transmitter (Condenser Fans)

The control setpoint is preset by **P04** as a pressure value (this is the setpoint for stage 1 at the same time), no access code necessary. The following stages switch in a distance to the previous stage (**P05-P11**). The hysteresis **P14** is located symmetrical around the setpoints

<u>Forward (Stages on)</u> If the measured pressure value exceeds one of the **setpoints +** $\frac{1}{2}$ **P14** (hysteresis), the forward delay **P28** starts. After this timer is run down, the corresponding stage will switch and the timer starts again. P42 shows a running delay time up to the next stage will switch.

<u>Neutral zone</u> If the actual pressure value is located within the hysteresis **P14** (located around all setpoints), no stage will be activated or de-activated.

Backrun (Stages will switch off)

If the actual pressure value falls short of a setpoint - 1/2 P14, the backrun delay P29 starts. After this timer is run down, the corresponding stage will switch off, the timer starts again, and so on.

potential free contact). Functions depending on analog signals are not available if this kind of probe is selected.

Forward (Stages on)

If the Pressostat is switched to 'Forward', the forward delay P28 starts. After this timer is run down, a stage switches ON and the timer starts again. Read at P42 if a delay time is still running and when a stage will be switched on or off.

Neutral zone

If the contacts of the Pressostat are open (mid position), then no stage will be activated or de-activated.

Backrun (Stages will switch off)

If the Pressostat is switched to 'Backrun', the backrun delay P29 starts. After this timer is run down, one stage will switch off, the timer starts again, and so on.

Stage Controller for Brine-Chillers

The control setpoint is preset by **P04** as a temperature value (this is the set-point for stage 1 at the same time), no access code necessary. The following stages switch in a distance to the previous stages (**P05-P11**). The hysteresis **P14** is located symmetrical around the setpoints.

Forward (Stages on) If the measured temperature value exceeds one of the setpoints + 1/2 P14 (hysteresis), the forward delay P28 starts. After this timer is run down, the corresponding stage will switch and the timer starts again. P42 shows a running delay time up to the next stage will switch.

<u>Neutral zone</u> If the actual pressure value is located within the hysteresis **P14** (located around all setpoints), no stage will be activated or de-activated.

Backrun (Stages will switch off)

If the actual temperature value falls short of a setpoint - 1/2 P14, the backrun delay P29 starts. After this timer is run down, the corresponding stage will switch off, the timer starts again, and so on.

Motor/Machine/Load Control

The MSR-unit is able to control up to 4 single motors or multi-stage machines with up to four stages. By adding a 'slave'-module up to 8 stages are possible. The kind of machines and the number of stages are fixed by parameters P20-P27. Example:

Compressor / Fan	Programming							Relays used for Compressor / Fan								
	P20	P21	P22	P23	P24	P25	P26	P27	K1	K2	K3	K4	K5	K6	K7	K8
8x single mach.	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1x 6-stage	6	0	0	0	0	0	0	0	1.1	1.2	1.3	w	1.4	1.5	1.6	-
1x 6-stage	6	0	0	0	0	0	0	0	1.1	1.2	1.3	1.4	1.5	1.6	-	W
3x 2-stage	2	2	2	0	0	0	0	0	1.1	1.2	2.1	W	2.2	3.1	3.2	-
2x 2-stage and 2x single mach.	2	2	1	1	0	о	0	0	1.1	1.2	2.1	w	2.2	3	4	-

Which relay works as an alarm relay depends on the settings of P36. Rule of thumb: If the 4th stage (single operation of the unit) resp. the 8th stage (master/slave mode) is not used, this stage works as an alarm relay automatically. P31 determines if the alarm relay works active-on or active-off.

<u>Automatic Base Load Change (Stage Sequence Change)</u> The built-in base load change function (P33, ON/OFF) regards the relative runtimes of the single stages and cares for approximately the same motor runtimes by and by. If multistage machine types are used, only the runtime of the leading stage (= motor on) will be considered.

Load Limitation

Via one of the both digital inputs DI/OK1 and DI//OK2 a load limitation function can be initiated, e.g. for energy saving. P32 fixes how many stages remain for control purposes after this function has been started, the stages will be disabled within a few seconds.

Minimum Idle Time

If a load is switched off by a relay, this relay can be switched on again first after the time set with **P30** is over.

Relay Switching Mode

With P31 the switching mode of relay K1, K4 and K8 can be changed for special purposes:

- P31 = 0 All relays are active ON (will switch on), Standard setting P31 = 1 K1 active OFF (relay de-activated),
 - K4 and K8 (if available) active ON
 - With this setting e.g. an emergency operation can be realized, compressor 1 will be controlled by the N/C so it would run continuously if the MSR fails.
- P31 = 2 K1 active ON, K4 active OFF
 - Advisable if only 3 compressors/stages should be controlled and you want to use relay K4 as an active OFF **alarm relay**. K1 active OFF, K4 active ON, K8 active OFF
- P31 = 5 Can be used for emergency operation & alarm relay controlling 7 compressors or if compressor 1 and 8 should run in emergency mode.

Trend Analysis (STAN)

The stage controllers of the series MSR contain an autoadaptive algorithm to recognize actual value tendencies (STAN = Switch Tendency Analysis).

This algorithm effects an essential reduction of on/off cycles of the machines and a noticeable increased control accuracy. STAN works foreseeing, recognizes the trend of the actual value and decides about the necessity of switching on/off a machine, based on the captured data.

A typical example of a conventional control is the following state:

Machines run, the actual value approaches itself to the setpoint, the foreward delay of the next stage is still running. If the next stage will switch on now, the tendency will be increased, probably the setpoint range will be left quickly to low values. The high deviation to low values then effects mostly that multiple or all machines switch off and a quick rise of the pressure with essential overshoot of the setpoint range. The plant 'oszillates'.

This behaviour must be suppressed by increasing the switch delay times, but this makes the control slow and enables wider setpoint deviations

STAN avoids the effects in this example: STAN recognizes that the actual value moves to the setpoint direction and disables that machines (stages) will switch on. If the tendency continues, the setpoint will be reached without additional power. Oszillating or essential decreasing of the setpoint range will be avoided safely.

STAN works complety autoadaptive, no parameters must be set. Because of the fuzzy logic of the algorithm, disadvantageous effects like moving setpoint deviations will be recognized, so they cannot affect the tendency analysis.

If the MSR works as a brine/chiller ĭ controller, STAN keeps disabled.

The single Advantages:

- Essential reduction of on/off cycles and so an increased lifetime of components, especially of compressors.
- More accurate, more regular control with less setpoint deviations than a standard stage controller. This affects lower energy consumption and the cold production works
- with a constant, high efficiency ratio. Expansion valves work more regular and so more efficient, based upon the lower suction resp.condenser pressure variations. The average 'delta T' falls. This affects a
- lower icing of the evaporators, and the product quality rises because of the lower de-humidifying (counters of meat/cheese, meat storages)
- The reaction times of the plant meet the demands, because the delay times must not be increased additionally to damp the switching behaviour.
- Autoadaptive, no settings necessary

Digital Inputs

The digital inputs DI/OK1 andDI/OK2 are normally (depending on type) connected to mains voltage. If this voltage is interrupted, the functions set with **P34** and P35 will be initiated.



This contact must be suitable for 5VDC/1mA).

- 0= Digital Input is de-activated 1= No voltage at the input (1100-2: contact open) changes to the 2nd (night) setpoint.
- The internal time switch has no effect, that means the digital input has a prior rank. No voltage at the input (1100-2: contact open) initiates a **Peak Load Limitation.** The no. 2= of stages remaining for control purposes must be preset by P32.
- No voltage at the input (1100-2: contact open) 3= starts a Fast Backrun, all stages will switch off in 1 sec. steps



Note: To prevent from being activated un-intended, the functions of DI/OK1 and 2 are de-activated while programming parameters P34/P35.

If the same function is selected for both inputs. then DI/OK 2 has the higher priority.

Voltage Output / Analogue Output

The MSR-Controller owns an analogue output with a 0-10 V DC-signal, which can be used both to forward an image of the actual value P01 or as proportional controller output.

- P49.... fixes the actual value the analogue output delivers 10V (resp. 0V, if P51=2) DC voltage
- P50 fixes the actual value the analogue output delivers 0V (resp. 10V, if P51=2) DC voltage.
- P51.... switches the analog output ON or OFF and determines if the voltage should rise (P51=1) or fall (P51=2) if the actual value rises.

Example for a Actual Value Forwarding: You want to use a remote display or similar, which shows 0 bar with 0V input and 10 bar with 10V input.

P50 = "0", P49 = "+10", P51 must be "1".

Example for a Proportional Controller: You want to control a three-way valve. This valve should be half open at 5.0 bar. If the pressure falls, the valve should open, from 4 bar the valve should be full open. If the pressure rises, the valve should be narrowed, from 6 bar it should be closed.

P50 ="4.0", P49 ="6.0", P51 ="2"

Real time clock

The Controller contains a real time clock (without a date function) which can be used for changing the control setpoint. The timer has a data backup for about 10 days in case of power failure. The time of the day and the date can be set by parameters **P52 - P54**.

The time switch is de-activated if ON and OFF-time are identical.

Operation Time Counter

Each relay output owns an individual operation time counter. This counter measures and totalizes the time this output was activated. The values can be read at "r01" - "r08". Because the display has 3 digits only, the stored value is "*displayed value x 10*". After 9999 hours the counter will be reset to "0". A reset by the user is not possible.





Networking of MSR Controllers

Interface

All MSR controllers can be networked via their built-in RS-485-interface. This network can be controlled by a host unit. This host can be a PC with a qualified software or a SMZ-Frontend-System which allows remote control of units and recording of all parameters.



Exception: In "master mode" (P36 = 0 or 2) the interface is used fo connecting a slave module with 4 more stages.

- Because all units are connected parallel on the data bus, every unit has its own network address (**P56**) to ensure a specific communication. The communication speed is fixed with **P55**, (Default value 9600 Baud).
- Connection is done by commercial databus cable
- Shielding and ground connectors must be connected to the nearest
- The unshielded part of the data cable must be as short as possible.

If multiple, networked controller units are supplied from one transformer (MSR 1100-2 only), a double pole switch must be used to switch off the single positions. If not, the unit will be supplied by a half-wave via the shielding, and the unit Continues working (depending on the secondary voltage of the transformer). Please note: In this case a PC software announces a malfunction!



Stage extension by adding the 'Slave' module MSR 1100-2 S

Only possible in the combination MSR 1100-2 and MSR 1100-2 S !

- The MSR 1100-2 can be expanded up to 8 stages by adding a slave module MSR 1100-2 S-
- 'Master-' and 'Slave-' module must be regarded as a single unit. The MSR 1100-2 types can be supplied both by a single transformer or different transformers which must be switched together.
- The controllers must be mounted as close as possible to get a short data connection.
- Parameter P36 must be set to "0" or "2", so the MSR expects a slave module
- While communication problems to the slave error messages "E18" appears.
- With communication problems >30 sec. the stages of the slave switch off (beginning with K8) in 1 sec. steps. When the problem is eliminated the slave switches its stages on again, beginning with K5.
- If less than 8 stages are selected, the position of the alarm relay depends on P36



Startup Examples

MSR as Compressor Compound Controller

Requirement:

4 single compressors, stage 1 configured for emergency operation, automatic base-load change. Control setpoint2 bar, neutral zone 0,5 bar. pressure transmitter 4-20 mA, range 0-10 bar. Night operation (2nd setpoint) within 19:00 and 7:00, 0,5 bar higher. Forward/Backrun delay 10 sec. The user want to see the actual pressure value on a remote display with 0-10V-input. While a peak load limitation via DI/OK 1, 2 stages remain for control purposes.

Please always note the Safety Instructions!

Select Operation Mode • Switch OFF power supply

- Push and hold key 'P', switch ON power Hold key 'P' until '____'appears Release key 'P' Select '1____' by key 'û' (compressor mode) Select '1 ___' by Push key 'P' once
- def appears, default values are loaded
- Actual values appear, ready for start up.

Basic Configuration

i

Enter Code Number '70'

- P20=1 (single compressor at relay K1)
- P21=1 (single compressor at relay K2)
- P22=1 (single compressor at relay K3)
- P23=1 (single compressor at relay K4)
- P31=1 (relay K1 inverted, load at N/C) P33=1 (base load change ON) P37=4 (transmitter with 4-20 mA signal)
- i

Enter Code Number '88'

- Adjustments P40=10.0 (press. value transmitter at 20 mA)
- P41=0.0 (press. value transmitter at 4 mA) P04=2.0 (control setpoint)
- P10=0.5 (neutral zone / hysteresis)
- P28=10 (forward delay in sec.) P29=10 (backrun delay in sec.)
- P32=2 (2 stages remain after peak load lim.) P34=2 (DI/OK 1 configured for peak load lim.) P44=2.5 (2nd control setpoint)

- P45=19 (2nd setpoint ON 'hours') P46=00 (2nd setpoint ON 'minutes') P47=07 (2nd setpoint OFF 'hours') P48=00 (2nd setpoint OFF 'minutes')
- P49=10
- (analog output delivers 10VDC at 10 bar) È50=0
- (analog output delivers 0V at 0 bar)
- P51=1 (analog output works proportional)
- P52=--(clock time 'hours') P53=--(clock time 'minutes')
- P54=--(clock time 'seconds')

Display correction

The actual pressure display **P01** can be calibrated by using **P38**.

Extension with 2 more single compressors

A"slave" module is connected, settings like above. but additionally:

- P24=1 (single compressor at relay K5)
- P25=1 (single compressor at relay K6) P36=2 (slave module is expected, relay K8
- is now automatically an alarm relay, because it is not necessary for control purposes.
- P31=5 (Relay K1 inverted and alarm relay K8 inverted (if desired only)

MSR as Condenser Fan Controller

Requirement:

3 single fans, no emergency mode, automatic base-load change.

Control at 15, 16, 17 bar, neutral zone 0,5 bar each. Pressure transmitter 4-20 mA, range 0-25 bar. Night operation (2nd setpoint) within 20:00 and 6:30, 2 bar higher. Forward/Backrun delay 30 sec.

Please always note the Safety Instructions!

<u>Select Operation Mode</u> Switch OFF power supply

- Push and hold key 'P', switch ON power Hold key 'P' until '___' appears
- Let go key 'P'
- Select '2 _' by key '얍' (condens. fan mode)
 - Push key 'P' once
- 'def' appears, default values are loaded •
- Actual values appear, ready for start up.

Basic Configuration

i Enter Code Number '70'

- P20=1 (single fan at relay K1)
- P21=1 (single fan at relay K2
- P22=1 (single fan at relay K3) •
- P31=0 (no emergency mode, K1 not invert.)
- P33=1 (base load change ON) P37=4 (transmitter with 4-20 mA signal) .

i Enter Code Number '88'

- Adjustments P40=25.0 (press. value transmitter at 20 mA)
- P41=0.0 (press. value transmitter at 4 mA) P04=15.0 (control setpoint stage 1)
- . P05=1.0
- (setpoint stage 2 in a distance to P04) $\dot{P}06=10$
- (setpoint stage 3 in a distance to P05) P14=0.5 (neutral zone / hysteresis) P28=20 (forward delay in sec.)

- P29=20 (backrun delay in sec. .
- P44=17.0 (2nd control setpoint 1) .
- P45=20 (2nd setpoint ON 'hours')
- .
- P46=00 (2nd setpoint ON 'minutes') P47=06 (2nd setpoint OFF 'hours') P48=30 (2nd setpoint OFF 'minutes') .
- --(clock time 'hours')
- P53=--(clock time 'minutés') .
- P54=--(clock time 'seconds')

Display correction

The actual pressure display **P01** can be calibrated by using **P38**.

MSR as Brine-Chiller Controller

Requirement:

2 dual-stage compressors, no emergency mode,

Page 9

automatic base load change. Control at 4, 6, 8, 10 $^{\circ}$ C, hysteresis 0,5 K each. Temperature sensor TF 501, night operation (2nd setpoint) within 20:30 and 6:00, 2 K higher. Forward/Backrun delay 25 sec.



Let go key 'P'

Basic Configuration

P05=2.0

P06=2.0

P07=20

Display correction

outlet temperature).

i

i

.

.

.

.

•

.

.

Select '3 ___' by k Push key 'P' once

Please always note the Safety Instructions!

_' by key 'û' (Brine-Chiller mode)

(compr. 1 power stage ON, relay K2)

<u>Select Operation Mode</u>
Switch OFF power supply
Push and hold key 'P', switch ON power
Hold key 'P' until '____' appears

'def' appears, default values are loaded

Actual values appear, ready for start up.

Enter Code Number '70'

P20=2 (compressor 1 ON, relay K1)

P21=2 (compressor 2 ON, relay K3)

P37=2 (temperature sensor TF 501)

Enter Code Number '88'

(setpoint stage 2 in a distance to P04)

(setpoint stage 3 in a distance to P05)

(setpoint stage 4 in a distance to P06) P14=0.5 (neutral zone / hysteresis)

P28=25 (forward delay in sec.)

P29=25 (backrun delay in sec.

P52=--(clock time 'hours')

P53=--(clock time 'minutes')

P54=--(clock time 'seconds')

P44=6.0 (2nd control setpoint 1)

P45=20 (2nd setpoint ON 'hours') P46=30 (2nd setpoint ON 'minutes') P47=06 (2nd setpoint OFF 'hours')

P48=00 (2nd setpoint OFF 'minutés')

The 2 actual temperature displays can be calibrated by $P38\ (\ \text{P01},\ \text{inlet}\ \text{temperature})$ and $P39\ (\text{P02},$

Adjustments • P04=4.0 (control setpoint stage 1)

(compr. 2 power stage ON, relay K4) P31=0 (no emergency mode, K1 not invert.) P33=1 (base load change ON)

CONNECTION INFORMATION & SAFETY INSTRUCTIONS



CAUTION

The guarantee will lapse in case of damage caused by failure to comply with these operating instructions! We shall not be liable for any consequent loss! We do not accept liability for personal injury or damage to property caused by inadequate handling or non-observance of the safety instructions! The guarantee will lapse in such cases.

This manual contains additional safety instructions in the functional description. Please note them!

If you notice any damage, the product may not be connected to mains voltage! Danger of Life!

DANGER A riskless operation is impossible if:

- The device has visible damages or doesn't work
- · After a long-time storage under unfavourable conditions
- The device is strongly draggled or wet
- After inadequate shipping conditions
- · Never use this product in equipment or systems that are intended to be used under such circumstances that may affect human life. For applications requiring extremely high reliability, please contact the manufacturer first.
- The product may only be used for the applications described on page 1.
- · Electrical installation and putting into service must be done from qualified personnel.
- · During installation and wiring never work when the electricity is not cut-off ! Danger of electric shock!
- Never operate unit without housing. Danger of electric shock!
- All 'PE' terminals must be connected to ground. Danger of electric shock! Additionally, the internal noise filter will not work, faulty indicated values may occur.
- · Please note the safety instructions and standards of your place of installation!
- · Before installation: Check the limits of the controller and
- the application (see tech. data). Check amongst others: Make sure that all wiring has been made in accordance
- with the wiring diagram in this manual. Supply voltage (is printed on the type label).
- Environmental limits for temperature/humidity. - Maximum admitted current rate for the relays. Compare
- it with the peak start-up currents of the controlled loads (motors, heaters, etc.).

Outside these limits malfunction or damages may occur.

- Sensor/probe cables must be shielded. Don't install them in parallel to high-current cables. Shielding must be connected to PE at the end close to the controller. If not, inductive interferences may occur.
- · Please note for elongation: The wire gauge is not critical, but should have 0,5mm² as a minimum.
- · Mounting the controller close to power relays is unfavourable. Strong electro-magnetic interference, malfunction may occur!
- Take care that the wiring of interface lines meets the necessary requirements.
- All used temperature sensors must be identical. Never use different types at the same time. This will not work.
- TF-type sensors are not designed for being immersed in fluids permanently. In such a case, always use dip-fittings. With extreme temperature variations, the sensor may be damaged.

Cleaning

The use of a dry, lint-free cloth and household agents is sufficient to clean the product.

Notice Never use acids or acidic fluids! Risk of damage!

EC Declaration of Conformity									
For the devices MSR 1100-2, MSR 3100-2 and MSR 5100-2 we state the following: When operated in accordance with the technical manual, the criteria have been met that are outlined in the EMC Directive 2014/30/EC and the Low Voltage Directive 2014/35/EC. This declaration is valid for those products covered by the technical manual which itself is part of the declaration.									
Following standards were consulted for the conformity testing to meet the requirements of EMC and Low Voltage Guidelines: EN 55011:2016, EN 61010-1:2010, EN 61326-1:2013 CE marking of year: 2017									
This statement is made for the ma	This statement is made for the manufacturer / importer by:								
ELREHA Elektronische Regelungen GmbH Werner Roemer, <i>Technical Director</i>									
www.elreha.de Hockenheim 12.6.2017									
(Name / Address)		City	Date	Signature					
original set up: 13.6.17. tkd/ir	checked: 14.6.17. ek/ha	approved: 14.6.	17. mv/sha	korr.					