－Usable as：Temperature－，
Humidity－，Pressure－or Cold
Storage Controller
－Operation Modes：
－Double Single Setpoint，
－Dual Setpoint，
－Proportional－／PI－Controller，
－Step Controller，
－Setpoint shift by $2^{\text {nd }}$ sensor or 4.20 mA －input，
－Cold Storage Control with Cyclic Defrost
－Output 0－10VDC
－Limit value alarm，Alarm relay
－Inputs for PTC／Pt1000 and
4．．． 20 mA ，Digital Input
－Networkable via RS－485－Interface

Can be used for
－Cooling，Heating and HVAC Applications


Parameters（setpoints，times，etc．）
All selectable parameters hold a parameter number（e．g．P03），you will find a listing on the next page．

## Calling up and editing

Press key＇P＇． $\qquad$ parameter number appears
Use＇仓／／々＇
．．．．．．．．
$\qquad$ parameter val parameter
Use keys＇仓ি／ $\qquad$ parameter value appears

Press＇P＇again．．．．．．．．．．．．．．．．．value is stored，back to parameter no．

## Unlock Keys／Access code

To preventun－authorized persons fromediting parameter values，there is alocking function which allows only the most important parameters to be changed at any time．All other parameters must be unlocked as follows：
－enter access code before programming at parameter P46 or
－directly at the parameter to be changed．If a code no．is necessary the
display shows＂C00＂．Set the matching code no．by the＂仓／ノ＂－keys（70 or
80 ，see parameter listing）and confirm by＂P＂．
If no key is hit for about four minutes，the access code is cancelled and the editing function is locked automatically．

## Start－up behavior

Directly after start－up the display shows＂260＂（controller type），after that a display test passes．
How to find out the controller type
－Press key＂P＂for＞ 2 sec．＝Display shows controller type（260）
－Key＂$\Omega$＂additionally＝Software version is displayed
Manual controller＂wake－up＂
If the controller is switched off via interface（e．g．from a PC），the display shows ＂oFF＂．By holding key＂$\Omega$＂for $>3 \mathrm{sec}$ ．the controller unit engage．

## Manual Defrost

In cold storage controller mode（P14＝4）and while the actual value of sensor 1 is displayed，a defrost event can be initiated：
－Press key＂介＂for more than 2 seconds＝Defrost ON
－Press key＂Лु＂for more than 2 seconds＝Defrost OFF．

## Reset parameters to factory settings

Switch OFF supply voltage，pressandhold＂P＂－key，switch voltageONagain．Code request＂C＂appears．Enter＂ 88 ＂，confirm by＂P＂．One by one software version， date and＂def＂appear．With this，all values are reset to the factory settings．

## Please note Safety Instructions ！ <br> When replacing older types please note changed functions and connectors ！ <br> If your controller has a different software version， some functions could not be present ！

TAR 1260－2
from SoftwVers． TAR 3260－2 from SoftwVers．2．0．0 TAR 5260－2
from SoftwVers．2．0．1 1．0．5

Technical Data（see parameter listing for more information）
Supply Voltage
．see above
Output Relays $\qquad$ $.3 \times$ potential free
Contact Rating $\qquad$ ． 8 A resistive， $3 \mathrm{~A} \cos$ phi $0,4,250 \mathrm{~V}$ AC
TAR 1260－2（UL）． $\qquad$ resistive：120／240V AC，8A， 30 k cycles motor： $125 / 250 \mathrm{~V} \mathrm{AC}, 1 / 4 \mathrm{HP}, 30 \mathrm{k}$ cycles
Ambient Temperature TAR 1260－2（UL）
Ambient Temperature TAR 3260－2／5260－2． $-10 . .+65^{\circ} \mathrm{C}\left(14 . .149^{\circ} \mathrm{F}\right)$

Storage Temperature $\qquad$ $-10 . .+55^{\circ} \mathrm{C}\left(14 . .131^{\circ} \mathrm{F}\right.$ Relative Humidity．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．max．85\％r．H．，not condensing Signal Inputs $.2 x$ TF 201 （PTC）or TF 501 （Pt1000） $1 \times 4 \ldots 20 \mathrm{~mA}, 100$ ohms shunt
Transducer Supply ．．．．DC unregulated，depending on transformer，max． 35 mA Display
（1260－2）．．．．．．．．．．．．．．．．LED，7－segment，red，character height 13mm（． 51 inch）
（3260－2，5260－2）．．LED， 7 －segment，red，character height 11 mm （． 43 inch）

Control－／Display Range（with TF 201） $\qquad$ （
$\qquad$ $-40 . . .+80^{\circ} \mathrm{C} /-40 . . .176^{\circ} \mathrm{F}$
Data storage parameters $\qquad$ $\geq 20$ years
Relay indicators $\qquad$ depends on type（see below）
Digital input（OK／DI）． $\qquad$
Analog Output
tion． $\qquad$ 8 bit within
Analog Output Resolution $\qquad$
$\qquad$ 0 －10V DC，max． 3 mA Interface $\qquad$ screw terminals

E－Link（RS－485）
Electrical connection $\qquad$
／Digita Input
$.77 \times 35 \mathrm{~mm}$ front frame，IP 54 from front Digital input for external，potential free contact for rail mounting，IP 30
TAR 3260－2 Digital input for mains voltage， $50-60 \mathrm{~Hz}$ ，max．3mA ．．．．．．．．．．．．．．．． $96 \times 48 \mathrm{~mm}$ front frame，IP 54 from front Digital input for mains voltage， $50-60 \mathrm{~Hz}$ ，max． 3 mA
Further data you will find in the parameter listing．
Accessories（please order separately）
－Temperature sensor TF 201 （up to $80^{\circ} \mathrm{C}$ max．）or
Temperature sensor TF 501 （PT1000，up to $300^{\circ} \mathrm{C}$ ，dep．on type）or
－2－wire pressure transmitter，type DG．．or similar with 4－20 mA output
－Humidity transmitter FF 2520 with 4．．． 20 mA output
For type TAR 1260－2：Transformer 107－1300－0052（230V／12V／5VA） Attention！These transformers are not suitable to supply a transducer at the same time．


## Failure Display / Failure handling

## Sensor short circuit or broken

If one of the sensors is broken, disconnected or hot-wired, or the value is located outside of the specified range, the display shows "-- -" at first. After 1 minute the display flashes and shows an error code. The alarm relay will be activated at the same time.
Error Codes

| Error Codes |  |
| :---: | :---: |
|  | E06 .............. sensor F2 short circuit |
| E02 ..................essor F1 short circuit |  |
| E03 ......sensor F1 overtemperature | E08....... Sensor F 2 low temperature |
| F1 low temperature | E11....................... $4 / 20 \mathrm{~mA}$ input $<3 \mathrm{~mA}$ |
| sensor F2 broken | E12..................4/20mA input >21mA |

## Failure of Sensor 1 (control sensor) / Emergency Mode

If this sensor fails, the controller starts an emergency mode. Relay K1 then is clocking with a \%-part (P44) of a 30 minutes interval. With P44 $=0$ or 100 you can select if the relay is continuously on or off during this mode.
Display shows "oFF" if:

1. ...controller unit is switched OFF via digital input OK/DI1 or via network.
2. ...you select P02 or P28 and the evaporator sensor is switched off.

## Functional Description

## Sensor connection

The controller operates either with temperature sensors of the types TF201 and TF 501 (PT1000) orwith a $4 . . .20 \mathrm{mAsignal}$. The input can be selected by parameter P26

Ranges:
P26 = 1 (TF 201)......-50...+100º
P26 = 3 (TF 501/Pt1000).......-100... $+300^{\circ} \mathrm{C}$
With the settings P26 $=5$ or 6 the $4 \ldots 20 \mathrm{~mA}$
input will be activated and a probe type will
be assigned to the active probe input
Please note the specific temperature restrictions of the different sensor types (e.g.
$-40 \ldots+80^{\circ} \mathrm{C}$ with standard-TF-types) and ask for matching products if necessary.
Humidity-/Pressure Control:
Range dep. on transmitter, max. -100...+300

## Operation modes

The controller can be configured for different operating modes (by parameter P14):
P14 = 1: 2 control sensors
Sensor 1 effects on setpoint 1 (P03), sensor 2 effects to setpoint 2 (P04). Both setpoints are absolute values. So you realize
2 independent single stage temperature
controllers in one unit. In this mode the
4 ... 20 mA input is de-activated.
$\boldsymbol{P 1 4}=\mathbf{2}: \quad 1$ control sensor or 1 transmitter $4-20 \mathrm{~mA}$, for dual stage control.
Sensor input 1 or the $4 \ldots 20 \mathrm{~mA}$ signal input effects on both setpoints (P03 / P04), sensor input 2 is de-activated. P03 is an absolute value, P04 can be also relative (adj. by P05).
$P 05=1$ : Setpoint $2(P 04)$ is an absolute value (used for dual stage control with individual setpoints)
$\mathrm{P} 05=2$ : Setpoint $2(\mathrm{P} 04)$ is a relative value (used for dual stage control with neutral zone, that means that P04 will be shifted the same amount if P03 is shifted)
P14=3:
1 control sensor

+ 1 sensor for setpoint shift
Sensor 1 effects on setpoint 1 (P03), sensor 2 may shift setpoint 1 . The $4 \ldots 20 \mathrm{~mA}$ input is de-activated. With this, you realize e.g. an outdoor temperature guided control.
P19 is the limit from which a rise or lowering (shift) becomes possible, P20 is the range of the shift, P21 the amount of the shift.


Example:

- Control Setpoint $1 \quad P 03=10^{\circ} \mathrm{C}$
- Limit value $\quad P 19=20^{\circ} \mathrm{C}$, that means increasing starts with $20^{\circ}$ at sensor input 2, no shift below that value.
- range of shift
$P 20=5 K$, that means shift range is 25 K in total, above $25^{\circ} \mathrm{C}$ at sensor 2 maximum setpoint shift.
- Size of shift $P 21=8 K$, from $25^{\circ} \mathrm{C}$ the control setpoint is $\mathrm{P} 03+8 \mathrm{~K}$, in this example $=18^{\circ} \mathrm{C}$.

P18 shows the current shift amount. This value is a sum of the day/night shift and the setpoint shift.

P14 = 3: 1 control sensor
+4 ... 20 mA -input for setpoint shift The $4 . . .20 \mathrm{mAinput}$ can also be used for setpoint shifting. For that, you have to select " 5 " or "6" (depending on probe type) at P26. P29 and P30 defines the temperature range which is represented by the $4 . . .20 \mathrm{~mA}$ signal. With this settings, the signal replaces a temperature probe and will be displayed at P02.

P14 = 4: control sensors + cyclic defrost Sensor 1 effects on setpoint 1 (P03), sensor 2 effects on setpoint 2 (P04). With this configuration you realize two independent single stage controllers in one unit like above, but parameters 20/21 get a different function. Cooling via setpoint 1 (i.e. output effected by setpoint 1 ) is disabled in specific time intervals to enable air flow defrost.

P14 = 5: 2 different control sensors The 4-20mA input effects on setpoint 1 (P03), temp. sensor input F2 on setpoint 2. With this mode you can realize e.g. humidity control and temperature control at the same time.
The $4-20 \mathrm{~mA}$ input acts on the analog output..
$P 14=6: \quad 4 \ldots 20 \mathrm{~mA}$-input

+ 1 sensor for setpoint shift
Like P14=3, but with this setting the 4 ... 20 mA input can be used for control and the temperature sensor for setpoint shifting.


## Actual Value Display / Status Display

With temperature sensors: Temperatures can be displayed in ${ }^{\circ} \mathrm{C}$ or ${ }^{\circ} \mathrm{F}$ selected by parameter P26 (= sensor type switch). The resolution is $0.1^{\circ} \mathrm{C}$ (or $0,2^{\circ} \mathrm{F}$ ). While operating with temperature sensors, P01 shows the actual value of sensor 1 If another parameter is selected and no key is pressed for about 4 minutes, you come back to this parameter automatically. In op-modes P14=2, the P02 display is disabled.

With 4... 20 mA transmitters: In op-modes (P14) 2 and 5 the " $4 . . .20 \mathrm{~mA}$ "input is activated and can be read at P01.
The current signal can be delivered by any
4 ... 20 mA sources or appropriate transmitter.

## Adapting of transmitters, display correction

A transmitter delivers the measured value by a 4... 20 mA signal. Parameter P30/P29 presets the measuring scale.

$$
\begin{array}{lc}
\text { Example 1: } & \text { Humidity transmitter, } \\
\text { Range 0... } 100 \% & \text { r.H., P29 }=100, \mathrm{P} 30=0 \\
\text { Example 2: } & \text { Pressure transmitter, } \\
\text { Range }-0,5 \ldots+9.0 \text { bar, } \mathrm{P} 29=9.0, \mathrm{P} 30=-0.5
\end{array}
$$

With P 27 the display of actual value P 01 can be corrected, with P28 a correction of the value displayed by P02 is possible.

## Switching hysteresis

For the setpoints P03 / P04 you can fix a switching hysteresis with parameters P12 and P13. The position of the hysteresis (above/below the setpoint) depends on the selected relay switching mode (P07 resp. P08).

## Setpoint limits

To prevent the setpoints being setto an invalid value (e.g. not below $0^{\circ} \mathrm{C}$ ), the range of P03/P04 can be restricted by parameters P10 and P11.

## Day / night shift resp. $2^{\text {nd }}$ Setpoint

E. g. to save energy it is possible to switch to other setpoints at any time. By parameter P06 an offset value can be set on which all setpoints will be shifted if digital input OK/DI 1 is activated.

Temperature- resp. Limit Value Alarm
If the value measured with sensor 1 or the delivered $4 \ldots 20 \mathrm{~mA}$ signal leaves the range preset by parameters P32 and P33, the alarm relay will be activated after a delay timer (P31) is run down P22 shows the remaining time of the alarm delay timer. P33 (lowerlimit) is an absolute value and P32 is always a relative value coupled to the current setpoint (P03 + eventually shift).


Relay switching characteristic
The switching characteristic of relays K1 and K2 are defined by parameters P07 and P08.
The following options can be selected:
$1=$ Refrigeration (Standard)
Used for standard applications (e.g. temperatures above $0^{\circ} \mathrm{C}$ ). The load would
be switched by the N/O-contact.
Actual value = setpoint + hysteresis: Relay on
2 = Freezing (DF)
The load would be switched by the N/Ccontact, this enables that the load will be switched on permanently in case of mains loss or controller defect.
Actual value $=$ setpoint + hysteresis: Relay off

## Note: not usable for relay 2 at 1260-2.

## 3 = Heating (HT)

Usable for heating applications. Load would be switched off in case of mains fail or controller defect.
Actual value = setpoint - hysteresis: Relay on
4 = Cycling
Quasi-Proportional Control with cycling relay for heaters or certain valves. Here a range will be defined the relay will cycle within. The relay's ON/OFF ratio (cycle ratio) depends on control deviation. The period duration will be set by P40. With P40=1 the period duration is 16 seconds, with $\mathrm{P} 40=2$ the duration is 32 seconds, and so on.

## Cycling range of relay K1

Upper limit $=P 03$ (setp.1)
Lower limit = P03 (setp.1)-P16
Above this upper limit, relay 1 remains OFF permanently, below the lower limit relay 1 remains permanently ON (e.g. for heating, humidifying).

## Cycling range of relay K2

P05=1:
Lower limit $\quad=P 04$ (setp.2)
Upper limit $\quad=P 04$ (setp.2) + P17
P05=2:
Lower limit $\quad=P 03+P 04$
Upper limit $\quad=P 03+P 04+$ P17
Above this upper limit, relay 2 remains permanently ON (e.g. for refrigeration, de-humidifying), below the lower limit relay 2 remains OFF.

## Alarm relay characteristic

Parameter P09 defines if the alarm relay K4 is affected from the actual value P01 or P02 and whether the alarm relay is activated (active ON) or de-activated if an alarm occurs.

## Minimium idle time

If a relay has been switched OFF, it can be activated first after timer P15 is run down. This is valid for both control relays. If the relay switching characteristic is set to 'cycling' this function is de-activated.
Parameters P23 and P24 show the remaining time until the relays will switch ON again. The minimum idle time affects immediately after power-up of the controller.

## Defrost Function

In operation mode (P14=4) a simple defrost function can be used. This function suppresses (in adjustable intervals) the switch-on of relay 1 to enable an air circulation defrost.
The parameters P20 and P21 have another significance in this mode. P20 defines the defrost cycle, P21 the defrost duration
After power-on of the unit the defrost cycle time (P20) runs down first, before a defrost can start.


To prevent a temperature alarm while a defrost event, P31 must be lengthened eventually.
A defrost event can be started and stopped manually while the actual value is being displayed, while running it is indicated by a LED.

## (DH) Display Hold Function

This function allows to hold the lastmeasured actual temperature value on the display during a defrost cycle. After the defrost cycle has been terminated, the display shows the current measured value again. The DH-function can be initiated by P43.

## Digital Input

Digital input OK/DI1 is normally connected to mains voltage (not 1260-2). If this voltage is interrupted, the function set with P34 is initiated after a time delay ( P 35 ), which is adjustable within $0 . . .99 \mathrm{~min}$, at ' 0 ' the minimum delay is appr. 4 seconds. $\mathbf{P} 25$ shows the remaining delay time of the OK/DI.

## Using the TAR 1260-2 this function must

 be started by opening an external, potential free contact connected to terminals11/12. Never connect mains voltage to these terminals, danger of destruction! This contact must be suitable for $5 \mathrm{VDC} / 1 \mathrm{~mA}$.

P34 $=\mathrm{oFF}$ Digital Input is de-activated
P34 = $1 \quad$ The unit switches to the $\mathbf{2}^{\text {nd }} /$ nightsetpoint. Setpoints will be increased / decreased by the value of P06.
P34 $=2$ An external alarm will be detected after the time set by P35. After P31 is run down, LED 4 and the alarm relay will be activated.
P34 $=3$ All control functions are disabled, P01 shows 'oFF'. The unit can only be reactivated by closing the external contact. Relays, configured for freezing (P07 or P08 = 2) will engage.
Analogue output behaviour:

- Delivers $0 V$ with op-mode
proportional (P39=1 or 3).
- Delivers 10 V with op-mode anti-proportional (P39 = 2 or 4)


## Voltage Output / Analogue Output

The analog output comes with a 0-10 V DC-signal usable both for delivering an actual value 1 (P01) image or as a P/PI-control output.
P39 fixes the operation mode of the output.
P39=oFF..Output is de-activated.
P39=1..Output effects proportional, i.e. increasing actual value -> increasing output voltage. P36/P37 are the absolute actual values the output delivers $10 \mathrm{~V} / 0 \mathrm{~V}$.
P39=2.. Output effects anti-proportional, i.e increasing actual value -> decreasing output voltage. P36/P37 are the absolute values the output delivers $0 \mathrm{~V} / 10 \mathrm{~V}$.
P39=3 Output effects proportional (increasing actual value -> increasing output voltage), relative to the active setpoint (P03 + shift). P36/P37 define a proportional band around the active setpoint. Output voltage is 10 V at $\mathrm{P} 03+\mathrm{P} 36$ and 0 V at $\mathrm{P} 03-\mathrm{P} 37$.

$$
\begin{array}{ll}
\text { Example: } & \mathrm{P} 36=10^{\circ} \mathrm{C}, \mathrm{P} 37=-10^{\circ} \mathrm{C} \\
& \mathrm{P} 39=3, \mathrm{P} 03=15^{\circ} \mathrm{C}, \\
\text { Output } & 10 \mathrm{~V} \text { at } \mathrm{P} 03+\mathrm{P} 36=25^{\circ} \mathrm{C} \\
\text { voltages } & 0 \mathrm{~V} \text { at } \mathrm{P} 03+\mathrm{P} 37=5^{\circ} \mathrm{C}
\end{array}
$$

P39=4.. Output effects anti-proportional (increas. actual value $->$ decreasing outp. voltage), relative to the active setpoint.
P36/P37 define a proportional band around the active setpoint. Output voltage is 0 V at $\mathrm{P} 03+\mathrm{P} 36$ and 10 V at $\mathrm{P} 03-\mathrm{P} 37$.

Example: $\mathrm{P} 36=10^{\circ} \mathrm{C}, \mathrm{P} 37=-10^{\circ} \mathrm{C}$ $\mathrm{P} 39=3, \mathrm{P} 03=15^{\circ} \mathrm{C}$,
Output-: $\quad 0 \mathrm{~V}$ at PO3 $+\mathrm{P} 36=25^{\circ} \mathrm{C}$ voltages $\quad 10 \mathrm{~V}$ at $\mathrm{P} 03-\mathrm{P} 37=5^{\circ} \mathrm{C}$
Example Act. Val. Image (e.g. Remote Display): The output must deliver 0 V with $-50^{\circ} \mathrm{C}$ and 10 V at $+50^{\circ} \mathrm{C}$ : -> P37 = "-50", P36 = "+50", P39 = "1"
Example anti-proportional Controller:
Any device with $0-10 \mathrm{~V}$-input must be controlled depending on pressure, half open at 5.0 bar. With descending pressure the device should go more open, fully open from 4 bar. With increasing pressure the device must close, fully closed from 6 bar.
P37 ="4.0", P36 ="6.0", P39 ="2"

Slow-down time / l-part
P38 (slow-down time) fixes the effect of the I-part to the control process in 5 steps. The l-part amount of the controlling variable is identical with the $P$-part and will be added. The full size of the l-part will effect after P38 is run down.

## Example for a cycling heater:

Switching char.
.... P07 $=4$
Setpoint 1 . $\mathrm{P} 03=8^{\circ} \mathrm{C}$
P-range relay 1 P16 $=4 \mathrm{~K}$
$8^{\circ} \mathrm{C}=$ relay OFF permanently
$7^{\circ} \mathrm{C}=$ relay cycles, $25 \% \mathrm{ON}$, 75\% OFF
$6^{\circ} \mathrm{C}=$ relay cycles, $50 \% \mathrm{ON}$, 50\% OFF
$5^{\circ} \mathrm{C}=$ relay cycles, $75 \% \mathrm{ON}$, 25\% OFF
$4^{\circ} \mathrm{C}=$ relay ON permanently


Effects of the Slow-down time
When P39 = 1
Act.Val. $=$ Setpoint: Output $5 \mathrm{~V} \pm 1$-Part
Act.Val. > Setpoint: Output shifts with l-part to 10 V
Act.Val. < Setpoint: Output shifts with I-part to 0 V
When P39=2
Act. Val. $=$ Setpoint: Output $5 \mathrm{~V} \pm$ I-Part
Act.Val. > Setpoint: Output shifts with l-part to 0 V
Act.Val. < Setpoint: Output shifts with l-part to 10 V
When P39 = 3
P36/P37 define a proportional band around the
active setpoint. The output voltage is 10 V at
$\mathrm{P} 03+\mathrm{P} 36$ and 0 V at P03 + P37.
Act. Val. $=$ Setpoint: Output $5 \mathrm{~V} \pm \mathrm{I}-\mathrm{Part}$
Act.Val. > Setpoint: Output shifts with l-Part to 10 V
Act.Val. < Setpoint: Output shifts with I-Part to OV
When P39 = 4
P36/P37 define a proportional band around the active setpoint. The output voltage is 0 V at P03 + P36 and 10V at P03 + P37.
Act.Val. $=$ Setpoint: Output 5V $\pm$ I-Part
Act.Val. > Setpoint: Output shifts with I-Part to 0 V
Act.Val. < Setpoint: Output shifts with I-Part to 10 V

After an excursive change of the actual value the P-part is calculated from the max. output voltage and the proportional band:
$\mathrm{Ux}=(10 \mathrm{~V} /(|\mathrm{P} 36-\mathrm{P} 37|[\mathrm{K}]))^{*}$ delta Theta $[\mathrm{K}]$
Example: • $10 \mathrm{~V} \mathrm{U}_{\text {out }}$ at $+10^{\circ} \mathrm{C}, 0 \mathrm{~V} \mathrm{U}_{\text {out }}$ at $-10^{\circ} \mathrm{C}$

- aimed setpoint $0^{\circ} \mathrm{C}=5 \mathrm{VU}_{\text {out }}$
- current actual value $0^{\circ} \mathrm{C}$

Actual value increases by 2 K ->

- $\mathrm{U}_{\text {out }}$ rises to 6 V immediately
- $U_{\text {out }}^{\text {out }}$ continues rising, after P38 is run down, 7 V will be reached.


TAR 1260-2 and Servo Drives / Actuators
CAUTION Actuators work with 24 V AC mostly and so you get the thought to supply actuator and controller from the same source. Unfortunately, supply voltage and control input are not isolated in actuators, this may destroy the TAR. Because of this:
If a TAR 1260-2 must control a servo drive, the TAR must be supplied by a separate transformer!


Please note the decreased lifetime of the relay contacts in cycling operation. Please care for a suitable relief.

Cycle 16 sec.:
load current 0,8A res. --> 2 years
load current 1,2A res. --> 1 year
load current 1,9A res. --> 0,5 years
(Theoretical values according to the relays data sheet)

TAR 1260-2 - Dimensions
dimensions in: mm (inches)


Connection \& Application Examples (simplified)

refrigeration/heating, outdoor temperature guided Basic settings: $\mathrm{P} 14=3, \mathrm{P} 07=1, \mathrm{P} 08=3, \mathrm{P} 26=1 . .4$

refrigeration 1/ refrigeration 2
Basic settings: $P 14=2, P 07=1, P 08=1, P 26=1 \ldots 4$


Humidity- / Temperature control simultaneously
Basic settings: $\mathrm{P} 14=5, \mathrm{P} 07=1, \mathrm{P} 08=1, \mathrm{P} 26=$ depending on sensor, $P 29=100, P 30=0$


Moisturize / de-humidifying
Basic settings: $P 14=2, P 07=1, P 08=3, P 26=5, P 29=100, P 30=0$

## Networking of TAR controllers

All controllers can be networked to a host (PC or SMZ) via their built-in RS-485-interface, which allows remote control of units and recording of all parameters.

- Because all units are connected parallel on the data cable, every unit has its own network address (P42) to ensure a specific communication. !! NOTE: Never use address 64 !!
- The data transmission speed is fixed by P41, the default value is 9600 Baud.
- Wiring must be made by standard data cable.
- Shieldings must be connected to the nearest grounding terminal.
- The unshielded part of the data cable must be as short as possible.

If networked controllers (1260-2 types only) are supplied by one transformer only and the single positions must be switched off, use double-pole switches only. If not, the unit will be supplied partially over the shielding of the data connection and continues operation, depending on the secondary voltage of the transformer. Please note: If a unit is not supplied, the PC-software notifies a unit breakdown!
A better way is not to switch-off the supply voltage but to disable the unit by Digital Input.

[^0]
## Dimensions / Wiring TAR 3260-2



Temperature Sensor Connection




Humidity Sensor Connection


Pressure Transducer Connection




The controller is not suitable for connecting 3 -wire pressure transducers.

## Dimensions / Wiring TAR 5260-2



Panel housing acc. to DIN 43700 / IEC 61554 cut-out: $92 \times 45 \mathrm{~mm}(\mathrm{w} \times \mathrm{h})$ tolerances max: $+0,8(\mathrm{w}),+0,6(\mathrm{~h})$


## Start-up Examples

## Dual Channel Temperature Controller

## Requirements:

Cooling ON at $+10^{\circ} \mathrm{C} /$ OFF at $+9^{\circ} \mathrm{C}$, Heating ON at $+1^{\circ} \mathrm{C} /$ OFF at $+2^{\circ} \mathrm{C}$, the offset Heating/Cooling remains always equal, Overtemperture Alarm at $+15^{\circ} \mathrm{C}$, Undertemperature Alarm at $0^{\circ} \mathrm{C}$, both after 30 minutes.
The alarm relay works active-low. At a certain time the setpoint must be increased by 2 K (night operation). The controller works with the temperature sensor TF 201. The customer must be prevented from adjusting the setpoint lower than $0^{\circ} \mathrm{C}$.

## - Please always note safety instructions!

If the TAR is switched ON, the display shows the value of sensor input 1.

1 Enter code number "70" at parameter P46

- P26= 1, Sensor Type TF 201 and display in ${ }^{\circ} \mathrm{C}$
- P14= 2, Operating mode with 1 control sensor (F1) only

1 Enter code number "88" at parameter P46

- $P 03=9.0$ (cooling setpoint, relay K1)
- P04 $=-7.0$ (heating setpoint 7 K below P03, relay K2)
- P05= 2 (heating setpoint is relative value, coupled to the cooling setpoint)
- $\quad \mathrm{PO6}=2.0$ (cooling setpoint will be increased by 2 K while night operation)
- $\quad \mathrm{P} 07=1$ (relay K 1 will be activated with rising temperature)
- $\mathrm{P} 08=3$ (relay K2 will be activated with falling temperature $=$ Heating $)$
- P09= 1 (alarm relay K4 will be de-activated with an alarm)
- P10= 15 (the setpoint cannot adjusted higher than $+15^{\circ}$ )
- P11=0 (the setpoint cannot adjusted lower than $0^{\circ}$ )
- P12= 1 (hysteresis of cooling relay, 1K)
- $P 13=1$ (hysteresis of heating relay, 1K)
- P31 = 30 (alarm delay 30 minutes)
- P32=5 (overtemperature alarm 5 K higher than cooling setpoint)
- P33= 0 (underemperature alarm at $0^{\circ}$ )
- P34=1 (digital input open = night shift)
- P35= 0 (night shift works immediately)

Display Correction
The Actual Value Display P01 can be adjusted by P27, the Actual Value Display P02 can be adjusted by P28.

## TAR as Humidity Controller

## Requirements:

De-humidifying ON at 80\% r.H., moisten ON at 60\% r.H., hysteresis $2 \%$, both setpoints are absolute values, no alarm, no night shift.
The controller mustwork with the humidity transmitter FF 2520.
No setpoint limitation for the customer.
The customer wants to read the humidity value on a remote display with 0-10V-input.

## - Please always note safety instructions!

If the TAR is switched ON, the display shows the value of sensor input 1.

1 Enter code number "70" at parameter P46

- $\mathrm{P} 26=5$, Transmitters with $4-20 \mathrm{~mA}$ signal
- P14=2, Operating mode with 1 control sensor only
1 Enter code number "88" at parameter P46
- P03=78.0 (de-humidify setpoint, relay K1)
- $\quad P 04=62.0$ (moisten setpoint, relay K2)
- $\quad \mathrm{P} 05=1$ (setpoints are absolute values)
- P06=0 (no setpoint shift)
- $P 07=1$ (relay K1 will be activated by rising humidity = de-hum.)
- $\quad$ P08 $=3$ (relay K2 will be activated by falling humidity $=$ hum.)
- $\mathrm{P} 10=100$
- $\mathrm{P} 11=0$
- P12= 2 (hyst. for de-humidifying relay, $2 \%$ )
- P13= 2 (hysteresis for moistening relay, 2\%)
- P29= 100 (display value with 20 mA current input)
- $\quad \mathrm{P} 30=0$ (display value with 4 mA current input)
- P34=0 (Digital input disabled)
- P36= 100 (Analog output delivers 10V DC at 100\% r.H.)
- P37=0 (Analog output delivers 0 V at $0 \%$ r.H.)
- P39= 1 (operating mode of analogue output)

Display Correction
The actual value display P01 can be adjusted by P27.

## Installation hint:

If the measured values 'jump' check the following: Is the shielding of the sensor wire connected to PE near the controller unit? Is the PE terminal of the controller unit connected to PE? If the sensor wire is shielded correctly but the value on the display continues 'jumping', please try to solve the problem by removing the shield from PE and connecting it to a ground terminal of the TAR.

## CONNECTION INFORMATION \& SAFETY INSTRUCTIONS

The guarantee will lapse in case of damage caused by failure to comply with these operating instructions! We shall not be liable for any consequent loss! We do not accept liability for personal injury or damage to property caused by inadequate handling or non-observance of the safety instructions! The guarantee will lapse in such cases.

This manual contains additional safety instructions in the functional description. Please note them!
If you notice any damage, the product may not be connected to mains voltage! Danger of Life!
DANGER A riskless operation is impossible if:

- The device has visible damages or doesn't work
- After a long-time storage under unfavourable conditions
- The device is strongly draggled or wet
- After inadequate shipping conditions
- Never use this product in equipment or systems that are intended to be used under such circumstances that may affect human life. For applications requiring extremely high reliability, please contact the manufacturer first.
- The product may only be used for the applications described on page 1.
- Electrical installation and putting into service must be done from qualified personnel.
- During installation and wiring never work when the electricity is not cut-off ! Danger of electric shock!
- Never operate unit without housing. Danger of electric shock!
- All 'PE' terminals must be connected to ground. Danger of electric shock! Additionally, the internal noise filter will not work, faulty indicated values may occur.
- Please note the safety instructions and standards of your place of installation!
- Before installation: Check the limits of the controller and the application (see tech. data). Check amongst others: - Make sure that all wiring has been made in accordance with the wiring diagram in this manual.
- Supply voltage (is printed on the type label).
- Environmental limits for temperature/humidity.
- Maximum admitted current rate for the relays. Compare it with the peak start-up currents of the controlled loads (motors, heaters,etc.). Outside these limits malfunction or damages may occur.
- Sensor/probe cables must be shielded. Don't install them in parallel to high-current cables. Shielding must be connected to PE at the end close to the controller. If not, inductive interferences may occur.
- Please note for elongation: The wire gauge is not critical, but should have $0,5 \mathrm{~mm}^{2}$ as a minimum.
- Mounting the controller close to power relays is unfavourable. Strong electro-magnetic interference, malfunction may occur!
- Take care that the wiring of interface lines meets the necessary requirements.
- All used temperature sensors must be identical. Never use different types at the same time. This will not work.
- TF-type sensors are not designed for being immersed in fluids permanently. In such a case, always use dip-fittings. With extreme temperature variations, the sensor may be damaged.

Cleaning
The use of a dry, lint-free cloth and household agents is sufficient to clean the product.

## Modifications of the $\mathbf{- 2}$ series

Modified terminals and electrical connections
Error messages now available as codes + error listing

- Access codes can be entered at any parameter now.
- 3 new parameters added, code parameter is now P46


## EC Declaration of Conformity

For the devices TAR 1260-2, TAR 3260-2 and TAR 5260-2 we state the following:
When operated in accordance with the technical manual, the criteria have been met that are outlined in the EMC Directive 2014/30/EC and the Low Voltage Directive 2014/35/EC. This declaration is valid for those products covered by the technical manual which itself is part of the declaration.
Following standards were consulted for the conformity testing to meet the requirements of EMC and Low Voltage Guidelines:
EN 55011:2016, EN 61010-1:2010, EN 61326-1:2013
CE marking of year: 2017

This statement is made for the manufacturer/importer
ELREHA Elektronische Regelungen GmbH D-68766 Hockenheim
www.elreha.de
(Name / Address)


| set up: $12.6 .17, \mathrm{tkd} / \mathrm{jr}$ | checked: $14.6 .17, \mathrm{ek} / \mathrm{ha}$ | approved: $14.6 .17, \mathrm{mv} / \mathrm{sha}$ | transl.(E): | transl.(F): | corr: |
| :--- | :--- | :--- | :--- | :--- | :--- |


[^0]:    Important: Never connect the secondary coil of the transformer to PE!
    Danger of destruction with networking!

