#### **Brief Description**

- · Usable as: Temperature-, Humidity-, Pressure- or Cold Storage Controller
- Operation Modes: - Double Single Setpoint,
- Dual Setpoint,
- Proportional-/ PI-Controller,
- Step Controller,
- Setpoint shift by 2nd sensor
- or 4..20mA-input,
- Cold Storage Control with Cyclic Defrost
- Output 0-10VDC
- Limit value alarm, Alarm relay
- · Inputs for PTC/Pt1000 and

**Operating Elements** 

- 4...20 mA, Digital Input
- Networkable via RS-485-Interface

### Can be used for

Cooling, Heating and HVAC Applications

Op-Mode 3: Setpoint shifted Op-Mode 4: Defrost runs



Technical manual

5311032-53/20E

## Temperature, Humidity, Pressure Controller

# TAR 1260-2 (1) from SoftwVers. TAR 3260-2 from SoftwVers. 2.0.0 TAR 5260-2 from SoftwVers. 2.0.1



#### Technical Data (see parameter listing for more information)

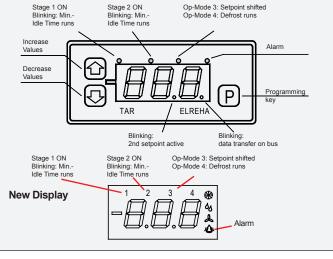
Supply Voltage	see above
Output Relays	3x potential free
Contact Rating	8A resistive, 3A cos phi 0,4, 250V AC
TAR 1260-2 (UIL)	resistive: 120/240V AC, 8A, 30 k cycles
	motor: 125/250V AC, <sup>1</sup> / <sub>4</sub> HP, 30 k cycles
Ambient Temperature TAR 1260-2 (I	$-10 + 65^{\circ}C (14 - 140^{\circ}E)$
Ambient Temperature TAP 3260 2/	L)10+65°C (14149°F) 5260-210+55°C (14131°F)
Storage Temperature	200-2
Storage remperature	
Relative Humidity	max. 85% r.H., not condensing
Signal Inputs	2x TF 201 (PTC) or TF 501 (Pt1000)
	1x 420mA, 100 ohms shunt
Transducer Supply DC unregulate Display	ed, depending on transformer, max. 35 mA
	nt, red, character height 13mm (.51 inch)
	nt, red, character height 11mm (.43 inch)
Resolution / Accuracy	0,1°C / 0,2°F / typ. ±1K
Control-/Display Range max	
Control-/Display Range (with TE 20)	1)
Data storage parameters	≥20 years
Relay Indicators	
	depends on type (see below)
Analog Output	0-10V DC, max. 3 mA 8 bit within the set benchmarks
Analog Output Resolution	
Interface	<i>E-Link</i> (RS-485)
Electrical connection	<i>E-Link</i> (RS-485) screw terminals 2,5mm <sup>2</sup> (.1 inch)
Housing / Protection / Digital Input	
TAR 1260-2	.77 x 35 mm front frame, IP 54 from front
TAR 3260-2	for rail mounting, IP 30
Digital inp	ut for mains voltage, 50-60Hz, max. 3mA
TAR 5260-2	.96 x 48 mm front frame, IP 54 from front
	ut for mains voltage, 50-60Hz, max. 3mA
Digital Inp	at for mains voltage, so-ouriz, max. SmA

Further data you will find in the parameter listing.

#### Accessories (please order separately)

- Temperature sensor TF 201 (up to 80°C max.) or Temperature sensor TF 501 (PT1000, up to 300°C, dep. on type) or 2-wire pressure transmitter, type DG.. or similar with 4-20 mA output Humidity transmitter FF 2520 with 4...20mA output
- For type TAR 1260-2: Transformer 107-1300-0052 (230V / 12V / 5VA). Attention! These transformers are not suitable to supply a transducer at the same time

Please read these instructions carefully before applying power. Your attention is drawn to the fact that the warranty is subject to the application of power sources that are within the limits specified in this manual. This documentation was compiled with utmost care, however, we cannot guarantee for its correctnesss in every respect. Technical details can be changed without notice, especially the software. Please note that the described functions are only valid for units containing the software with the version-number show no page 1. Units with an other software number can work a little bit different. You can request this software number at any time software number at the display at any time. ELREHA GmbH



#### Parameters (setpoints, times, etc.)

All selectable parameters hold a parameter number (e.g. P03), you will find a listing on the next page.

#### Calling up and editing

Press key 'P'	parameter number appears
Use 'û/∜'	select desired parameter (hold key for autoscroll)
Press "P" again	parameter value appears
	adjust parameter value (hold key for autoscroll)
Press 'P' again	value is stored, back to parameter no.

#### Unlock Keys / Access code

To prevent un-authorized persons from editing parameter values, there is a locking function which allows only the most important parameters to be changed at any time. All other parameters must be unlocked as follows: or

- enter access code before programming at parameter P46
- directly at the parameter to be changed. If a code no. is necessary the display shows "C00". Set the matching code no. by the "1/2"-keys (70 or
- 80, see parameter listing) and confirm by "P"

If no key is hit for about four minutes, the access code is cancelled and the editing function is locked automatically.

#### How to find out the controller type

#### Manual Defrost

In cold storage controller mode (P14=4) and while the actual value of sensor 1 is displayed, a defrost event can be initiated: - Press key "û" for more than 2 seconds = Defrost ON - Press key "<sup>0</sup>," for more than 2 seconds = Defrost OFF.

Reset parameters to factory settings Switch OFF supply voltage, press and hold "P"-key, switch voltage ON again. Code request "C" appears. Enter "88", confirm by "P". One by one software version, date and "def" appear. With this, all values are reset to the factory settings.



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### Start-up behavior

Directly after start-up the display shows "260" (controller type), after that a display test passes.

- Press key "P" for > 2 sec. = Display shows controller type (260)
- Key "<sup>1</sup>," additionally = Software version is displayed

**Manual controller "wake-up"** If the controller is switched off via interface (e.g. from a PC), the display shows "**oFF**". By holding key "<sup>1</sup>," for > 3 sec. the controller unit engage.

arameter listing	Co de	Description	Range	Factory Settings
P14=1 P14=2 P14=3 P14=4 P14=4				
	-	Astrophysics of a supervision without a	- Realized and a l	
<b>1</b>	<	Actual value of sensor/transmitter 1	display only !	
	<	Actual value of sensor 2 Control setpoint 1 (Absolute value)		0
	2 88	Control setpoint 1 (Absolute/Relative, depends on P05	within P10 and P11	0
•	00.	Relative value may also be negative.		.0
		Range with $P14 = 1,4$ or 5 : within $P11P10$		
		Range with $P14 = 2$ or 3. complete control range)		
5 x x		Mode of setpoint 2		.1
6x x x x	( 88.	Setpoint-Offset (Value the setpoints will be shifted		.0
_		while digital input OK1 is activated for 2nd setp. shift)		
7X X X X X	(188.	Switching mode of relay 1		.1
		Switching mode of relay 2	<b>3</b> = Heating (= moisten), <b>4</b> = Cycling	1
		Switching mode of alarm relay	<b>1</b> = <b>1</b> = <b>1</b>	. 1
3	00.		if P01 is too high/low	. 1
			<b>3</b> = de-activated, <b>4</b> = activated	
			if P02 is too high/low	
0x x x x x x	( 88.	Highest setpoint adjustable with P03 resp. P04		. +50
1	( 88.	Lowest setpoint adjustable with P03 resp. P04		50
2	( 88.	.Hvsteresis of control setpoint 1 (relav 1)	0.2.20	.2.0
3	(l 88.	Hvsteresis of control setpoint 2 (relav 2)		. 2.0
4X X X X.X	( <b>  70</b>	Operation Mode		.2
			2 = 1x temperature sensor or transmitter	
			3 = 1x temperature sensor + 1x shift sens. 4 = 1 = 1, add, cyclic defrost	
			<b>5</b> = sensor 1:  4-20mA; sensor 2: Temp.	
			6 = sensor  1: 4-20mA; + 1  shift sensor	
5x x x x x x x x x x x x x x x x x x x x	( 88.	Minimum Idle Time (relays 1 & 2)		.0
6 x l x l x l x l x	( 88.	Proportional range rel 1 (Heating resp. moisten)	0.12	.2.0
7	( 88.	Proportional range rel.2 (Heating resp. moisten)		. 2.0
8 x		Sum of all current setpoint shifts (offset + setpoint shift)	display only !	-
9 x	88.	Limit value of setpoint shift		.0
0 x		Range of shift	100+100K	.0
1 x	88.	Size of shift	100+100K	.0
0x	88.	Defrost cycle (h)Only if P14=4	1100 h	.4
				. 45
2 x x x x x	<	Remaining time alarm relay	display only !	
3lxlxlxlxl	<	. Remaining idle time relay 1	display only !	
4x x x .x .x	<	Remaining idle time relay 2 Remaining time digital input delay (OK)	display only !	
5X X X X X	<	Remaining time digital input delay (OK)		
6X X X X X	(170)	Sensor type	1 = TF 201 (°C), 2 = TF 201 (°F)   3 = TF 501 (°C).	. 1
		With operation mode P14=1 or 4 only 1-4 is possible. With operation mode P14=2 or 3 all types are possible.	4 = TF 501 (°F)	
		With opmode P14=5 or 6 only the settings 5 and 6 are	$5 = 420 \text{ mA} / \text{TF} 201, ^{\circ}\text{C}$	
		reasonable.	6 = 420 mA / TF 501, °C	
7 x x x x x	( 88.	Sensor / Transmitter 1 correction	-10.0+10.0	.0
8 x x .x .:	( 88.	Sensor 2 correction	oFF, -10,0+10,0	.0
9 x	( 88.	Displayed value at 20 mA signal current		. 100
0 x	( 88.	Displayed value at 4 mA signal current		. 0,0
1X X X.X.X	(188.	Alarm delay		.5
∠X X X X X	(188.	Upper Alarm Limit ( <i>Relative, related to the current</i>		. 100
3	00	setpoint P03 + the P06 offset) Lower Alarm Limit (Absolute value)	-100 +300	100
<b>4</b>	2 88	Digital input OK/DI 1	oFF, 1 = night setpoint (2nd setp.)	
	00.		2 = ext. alarm,  3 = controller OFF	-
5 x   x   x   x	( 88.	Delay time for digital input OK/DI1		.2
6x   x   x   x   x	( 88.	Analog output: 10V DC if actual value P01 =		. 50,0
7x x x x x .	( 88.	Analog output: 0V if actual value P01 =		50,0
8X X X.X.	( 88.	Analog output: slow-down time (I-part)	oFF, 1 = ~0,25 min, 2 = ~0,5 min	.oFF
			$3 = -1 \min 4 = -2 \min 5 = -4 \min 6$	
		Analog output: mode		.oFF
X	= Fu	nctions available in this mode,	2 = antiproportional 3 = proportional, relative to current setpoint	
<b>  1</b> v	/ithou	nctions available in this mode, t "x" = parameters invisible	4 = antiproport., relative to current setpoint	
		Factor of period duration		.1
		(Period duration = 16 sec. * factor)		
1x x x x x	( 88.	Data transmission speed (baudrate)		
			6=28800.7=57600	4
2 x x x x x	( 88.	Address of the controller in a network		.78
3x x x x .x .	( 88.	"Display Hold" (DH) while defrost		
		ON-time of the relay K1 while a sensor failure		
	1			. 50
		Current error + error listing	multiple errors present: scroll by 'û/&' keys	_

### Failure Display / Failure handling

#### Sensor short circuit or broken

If one of the sensors is broken, disconnected or hot-wired, or the value is located outside of the specified range, the display shows "- - -" at first. After 1 minute the display flashes and shows an error code. The alarm relay will be activated at the same time.

### **Error Codes**

E00ok	E06 sensor E2 short circuit
E01sensor F1 broken	E07sensor F2 overtemperature
E02 sensor F1 short circuit	E08 sensor F2 low temperature
E03sensor F1 overtemperature	E09failure at the digital input
E04 sensor F1 low temperature	
	E11 4/20mA input < 3mA
E05sensor F2 broken	E12

Failure of Sensor 1 (control sensor) / Emergency Mode If this sensor fails, the controller starts an emergency mode. Relay K1 then is clocking with a %-part (P44) of a 30 minutes interval. With P44 = 0 or 100 you can select if the relay is continuously on or off during this mode.

Display shows "oFF" if:
1. ...controller unit is switched OFF via digital input OK/DI1 or via network.
2. ...you select P02 or P28 and the evaporator sensor is switched off.



#### Functional Description

#### Sensor connection

The controller operates either with temperature sensors of the types TF201 and TF 501 (PT1000) or with a 4...20 mAsignal. The input can be selected by parameter P26.

#### Ranges<sup>.</sup>

P26 = 1 (TF 201).....-50...+100°C P26 = 3 (TF 501/Pt1000).....-100...+300°C With the settings P26 = 5 or 6 the 4...20mA input will be activated and a probe type will be assigned to the active probe input.

Please note the specific temperature restric-tions of the different sensor types (e.g. -40...+80°C with standard-TF-types) and ask for matching products if necessary.

Humidity-/Pressure Control:

Range dep. on transmitter, max. -100...+300

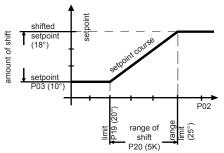
### **Operation modes**

The controller can be configured for different operating modes (by parameter **P14**):

- $P14 = 1^{-1}$ 2 control sensors Sensor 1 effects on setpoint 1 (P03), sensor 2 effects to setpoint 2 (P04). Both setpoints are absolute values. So you realize 2 independent single stage temperature controllers in one unit. In this mode the 20mA input is de-activated.
- P14 = 2: 1 control sensor or 1 transmitter 4-20mA, for dual stage control. Sensor input 1 or the 4...20 mA signal input effects on both setpoints (P03 / P04), sensor input 2 is de-activated. P03 is an absolute value, P04 can be also relative (adj. by P05).
  - P05 = 1: Setpoint 2 (P04) is an absolute value (used for dual stage control with individual setpoints) Setpoint 2 (P04) is a relative value
  - P05 = 2: (used for dual stage control with neutral zone, that means that P04 will be shifted the same amount if P03 is shifted)

#### P14=3:

1 control sensor + 1 sensor for setpoint shift Sensor 1 effects on setpoint 1 (P03), sensor 2 may shift setpoint 1. The 4...20 mA input is de-activated. With this, you realize e.g. an outdoor temperature guided control. P19 is the limit from which a rise or lowering (shift) becomes possible, P20 is the range of the shift, P21 the amount of the shift.



#### Example:

- P03 = 10°C - Control Setpoint 1 P19 = 20°C, - Limit value
- that means increasing starts with 20° at sensor input 2, no shift below that value. range of shift P20 = 5K,
- that means shift range is 25K in total, above 25°C at sensor 2 maximum setpoint shift. Size of shift  $P2\dot{1} = 8K$
- from 25°C the control setpoint is P03 + 8K, in this example = 18°C.



P18 shows the current shift amount. This value is a sum of the day/night shift and the setpoint shift.

#### P14 = 31 control sensor

- + 4...20mA-input for setpoint shift The 4...20mAinput can also be used for setpoint shifting. For that, you have to select "5" or "6" (depending on probe type) at **P26**. P29 and P30 defines the temperature range which is represented by the 4...20mA signal. With this settings, the signal replaces a temperature probe and will be displayed at P'02.
- I = 4: control sensors + <u>cyclic defrost</u> Sensor 1 effects on setpoint 1 (P03), sensor 2 effects on setpoint 2 (P04). With this confi- $P14 = 4^{\cdot}$ guration you realize two independent single stage controllers in one unit like above, but parameters 20/21 get a different function. Cooling via setpoint 1 (i.e. output effected by setpoint 1) is disabled in specific time intervals to enable air flow defrost.
- **4 = 5:** 2 different control sensors The 4-20mA input effects on setpoint 1 (**P03**), temp. sensor input F2 on setpoint 2. With this mode you can realize e.g. humidity control and temperature control at the P14 = 5: same time

The 4-20mA input acts on the analog output..

4...20mA-input + 1 sensor for setpoint shift P14 = 6:

Like P14=3, but with this setting the 4...20mA input can be used for control and the temperature sensor for setpoint shifting.

#### Actual Value Display / Status Display

With temperature sensors: Temperatures can be displayed in °C or °F selected by parameter P26 (= sensor type switch). The resolution is 0.1°C (or 0,2°F). While operating with temperature sensors, P01 shows the actual value of sensor 1. If another parameter is selected and no key is pressed for about 4 minutes, you come back to this parameter automatically. In op-modes P14=2, the **P02** display is disabled.

With 4...20 mA transmitters:

In op-modes (P14) 2 and 5 the "4...20 mA"input is activated and can be read at P01. The current signal can be delivered by any 4...20 mA sources or appropriate transmitter.

#### Adapting of transmitters, display correction

A transmitter delivers the measured value by a 4...20 mA signal. Parameter P30/P29 presets the measuring scale.

Example 1:

- Example 1: Humidity transmitter, Range 0...100% r.H., P29 = 100, P30 =0 Example 2: Pressure transmitter, Range –0,5 ... +9.0 bar, P29 = 9.0, P30 = -0.5 Example 2:

With P27 the display of actual value P01 can be corrected, with **P28** a correction of the value displayed by **P02** is possible.

Switching hysteresis For the setpoints P03 / P04 you can fix a switching hysteresis with parameters P12 and P13. The position of the hysteresis (above/below the setpoint) depends on the selected relay switching mode (P07 resp. P08).

#### Setpoint limits

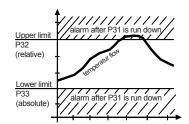
To prevent the setpoints being set to an invalid value (e.g. not below 0°C), the range of P03 / P04 can be restricted by parameters P10 and P11.

#### Day / night shift resp. 2nd Setpoint

E.g. to save energy it is possible to switch to other setpoints at any time. By parameter P06 an offset value can be set on which all setpoints will be shifted if digital input OK/DI 1 is activated.

#### Temperature- resp. Limit Value Alarm

If the value measured with sensor 1 or the delivered 4...20 mA signal leaves the range preset by parameters **P32** and **P33**, the alarm relay will be activated after a delay timer (P31) is run down. **P22** shows the remaining time of the alarm delay timer. P33 (lower limit) is an absolute value and P32 is always a relative value coupled to the current setpoint (P03 + eventually shift).



#### Relay switching characteristic

The switching characteristic of relays K1 and K2 are defined by parameters **P07** and **P08**. The following options can be selected:

- Refrigeration (Standard) Used for standard applications (e.g. temperatures above 0°C). The load would be switched by the N/O-contact. Actual value = setpoint + hysteresis: Relay on 2 = Freezing (DF)
- The load would be switched by the N/Ccontact, this enables that the load will be switched on permanently in case of mains loss or controller defect. Actual value = setpoint + hysteresis: Relay off

#### Note: not usable for relay 2 at 1260-2.

- 3 = Heating (HT)
  - Usable for heating applications. Load would be switched off in case of mains fail or controller defect.
- Actual value = setpoint hysteresis: Relay on Cycling Quasi-Proportional Control with cycling 4 =
  - relay for heaters or certain valves. Here a range will be defined the relay will cycle within. The relay's ON/OFF ratio (cycle ratio) depends on control deviation. The period duration will be set by P40. With P40=1 the period duration is 16 seconds, with P40=2 the duration is 32 seconds, and so on.

Cycling range of relay K1 Upper limit = P03 (setp.1) = P03 (setp. 1) - P16 Lower limit Above this upper limit, relay 1 remains OFF permanently, below the lower limit relay 1 remains permanently ON (e.g. for heating, humidifying).

## Cycling range of relay K2 P05=1:

= P04 (setp.2) = P04 (setp.2) + **P17** Lower limit Upper limit P05=2: = *P*03 + *P*04 = *P*03 + *P*04 + *P***17** Lower limit Upper limit Above this upper limit, relay 2 remains permanently ON (e.g. for refrigeration, de-humidifying), below the lower limit relay 2 remains OÉF

Alarm relay characteristic Parameter P09 defines if the alarm relay K4 is affected from the actual value P01 or P02 and whether the alarm relay is activated (active ON) or de-activated if an alarm occurs.

#### Minimium idle time

If a relay has been switched OFF, it can be activated first after timer **P15** is run down. This is valid for both control relays. If the relay switching characteristic is set to 'cycling' this function is de-activated. Parameters **P23** and **P24** show the remaining time

until the relays will switch ON again. The minimum idle time affects immediately after power-up of the controller.

Voltage Output / Analogue Output

<u> Slow-down time / I-part</u>

after P38 is run down.

the device must close, fully closed from 6 bar.

P37 ="4.0", P36 ="6.0", P39 ="2"

**P38** (slow-down time) fixes the effect of the I-part to the control process in 5 steps. The I-part amount

of the controlling variable is identical with the P-part

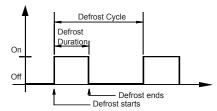
and will be added. The full size of the I-part will effect

### **Defrost Function**

In operation mode (P14=4) a simple defrost function can be used. This function suppresses (in adjustable intervals) the switch-on of relay 1 to enable an air circulation defrost.

The parameters P20 and P21 have another significance in this mode. P20 defines the defrost cycle, P21 the defrost duration.

After power-on of the unit the defrost cycle time (P20) runs down first, before a defrost can start.



To prevent a temperature alarm while a defrost event, P31 must be lengthened eventually A defrost event can be started and stopped manually while the actual value is being displayed, while running it is indicated by a LED.

#### (DH) Display Hold Function

This function allows to hold the last measured actual temperature value on the display during a defrost cycle. After the defrost cycle has been terminated, the display shows the current measured value again. The DH-function can be initiated by P43.

### **Digital Input**

Digital input OK/DI1 is normally connected to mains voltage (not 1260-2). If this voltage is interrupted, the function set with **P34** is initiated after a time delay (P35), which is adjustable within 0...99 min, at '0' the minimum delay is appr. 4 seconds. P25 shows the remaining delay time of the OK/DI.

Using the TAR 1260-2 this function must be started by opening an external, poten-11/12. Never connect mains voltage to these terminals, danger of destruction! This contact must be suitable for 5VDC/1mA.

P34 = oFF Digital Input is de-activated

The unit switches to the 2 <sup>nd</sup> /night-
setpoint. Setpoints will be increased
/ decreased by the value of P06.
An external alarm will be detected
after the time set by P35. After
P31 is run down, LED 4 and the
alarm relay will be activated.
All <b>control functions</b> are disabled,
P01 shows 'oFF'. The unit can only
be reactivated by closing the
external contact. Relays, configured
for freezing (P07 or P08 = 2) will
engage.
Analogue output behaviour:

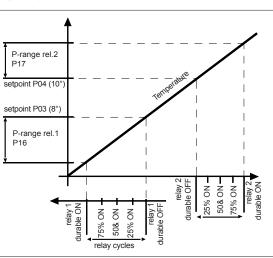
Delivers 0V with op-mode

- proportional (P39=1 or 3).
- Delivers 10V with op-mode anti-proportional (P39 = 2 or 4)

#### Example for a cycling heater:

5°C = relay cycles, 75% ON, 25% OFF

4°C = relay ON permanently



Voltage Output / Analogue Output	
The analog output comes with a 0-10 V DC-signal usable both for delivering an actual value 1 ( <b>P01</b> ) image or as a P/PI-control output.	Effects of the Slow-down time When P39 = 1 Act.Val. = Setpoint: Output 5V ± I-Part Act.Val. > Setpoint: Output shifts with I-part
<b>P39</b> fixes the operation mode of the output.	to 10V
<ul> <li>P39=oFF. Output is de-activated.</li> <li>P39=1. Output effects proportional, i.e. increasing actual value -&gt; increasing output voltage.</li> <li>P36/P37 are the absolute actual values the output delivers 10V / 0V.</li> <li>P39=2. Output effects anti-proportional, i.e. increasing actual value -&gt; decreasing</li> </ul>	Act.Val. < Setpoint: Output shifts with I-part to 0V When P39=2 Act.Val. = Setpoint: Output 5V ± I-Part Act.Val. > Setpoint: Output shifts with I-part to 0V Act.Val. < Setpoint: Output shifts with I-part
output voltage. <b>P36/P37</b> are the absolute values the output delivers 0V / 10V. P39=3 Output effects proportional (increasing actual value -> increasing output voltage), relative to the active setpoint (P03 + shift). <b>P36/P37</b> define a proportional band around the active setpoint. Output voltage is 10V at <b>P03 + P36</b> and 0V at <b>P03-P37</b> .	to 10V When P39 = 3 P36/P37 define a proportional band around the active setpoint. The output voltage is 10V at P03 + P36 and 0V at P03 + P37. Act.Val. = Setpoint: Output 5V ± I-Part Act.Val. > Setpoint: Output shifts with I-Part
Example:         P36 = 10°C, P37 = -10°C           P39 = 3, P03 = 15°C,           Output         10V at P03 + P36 = 25°C           voltages         0V at P03 + P37 = 5°C	to 10V Act.Val. < Setpoint: Output shifts with I-Part to 0V When P39 = 4 P36/P37 define a proportional band around the
<ul> <li>P39=4. Output effects anti-proportional (increas. actual value -&gt; decreasing outp. voltage), relative to the active setpoint.</li> <li>P36/P37 define a proportional band around the active setpoint. Output voltage is 0V at P03 + P36 and 10V at P03-P37.</li> </ul>	active setpoint. The output voltage is 0V at <b>P03</b> + <b>P36</b> and 10V at <b>P03</b> + <b>P37</b> . Act.Val. = Setpoint: Output 5V ± I-Part Act.Val. > Setpoint: Output shifts with I-Part to 0V Act.Val. < Setpoint: Output shifts with I-Part
<i>Example:</i> P36 = 10°C, P37 = -10°C	to 10V
P39 = 3, P03 = 15°C, Output-: 0V at P03 + P36 = 25°C voltages 10V at P03 - P37 = 5°C	After an excursive change of the actual value the P-part is calculated from the max. output voltage and the proportional band:
Example Act. Val. Image (e.g. Remote Display): The output must deliver 0V with -50°C and 10V at	Ux = (10V / ( P36 - P37  [K])) * delta Theta [K]
+50°C: -> P37 = "-50", P36 = "+50", P39 = "1" <i>Example anti-proportional Controller:</i> Any device with 0-10V-input must be controlled	Example: • 10V U <sub>out</sub> at +10°C, 0V U <sub>out</sub> at -10°C • aimed setpoint 0°C = 5V U <sub>out</sub> • current actual value 0°C
depending on pressure, half open at 5.0 bar. With	Actual value increases by 2K ->
descending pressure the device should go more open, fully open from 4 bar. With increasing pressure the device must deve filly cleared from 6 bar.	<ul> <li>U<sub>out</sub> rises to 6V immediately</li> <li>U<sub>out</sub> continues rising, after P38 is run</li> </ul>

- continues rising, after P38 is run
- down, 7V will be reached.



TAR 1260-2 and Servo Drives / Actuators

CAUTION Actuators work with 24V AC mostly and so you get the thought to supply actuator and controller from the same source.

Unfortunately, supply voltage and control input are not isolated in actuators, this may destroy the TAR. Because of this:

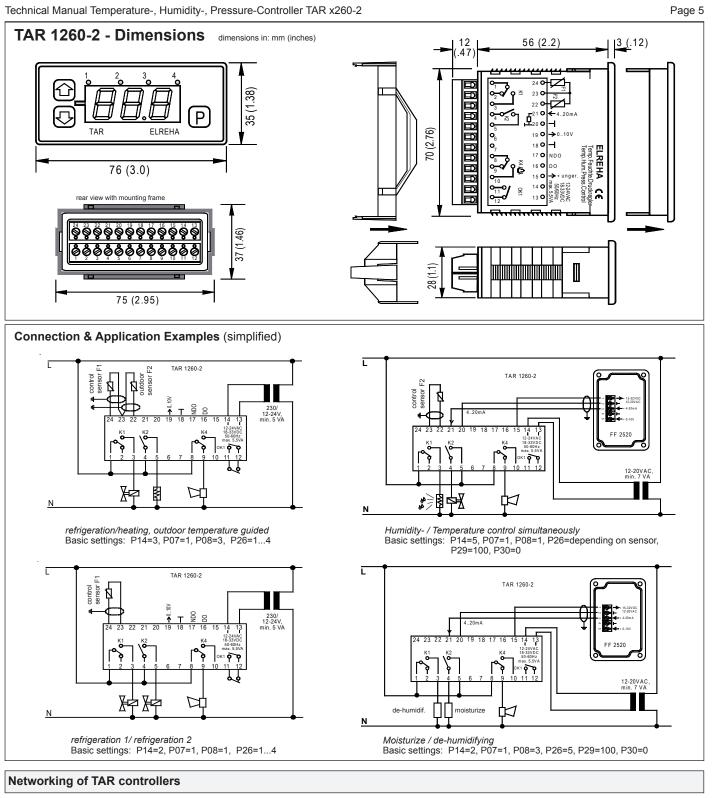
If a TAR 1260-2 must control a servo drive, the TAR must be supplied by a separate transformer !

Important !! --> CAUTION

Please note the decreased lifetime of the relay contacts in cycling operation. Please care for a suitable relief.

Cycle 16 sec.: load current 0,8A res. --> 2 years load current 1,2A res. --> 1 year load current 1,9A res. --> 0,5 years

(Theoretical values according to the relays data sheet)



All controllers can be networked to a host (PC or SMZ) via their built-in RS-485-interface, which allows remote control of units and recording of all parameters.

- Because all units are connected parallel on the data cable, every unit has its own network address (P42) to ensure a specific communication. !! NOTE: Never use address 64 !!
- The data transmission speed is fixed by P41, the default value is 9600 Baud.

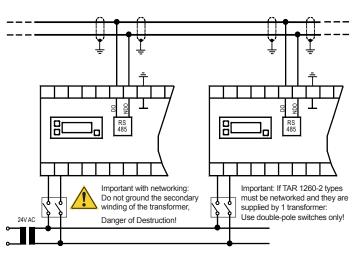
- Wiring must be made by standard data cable. Shieldings must be connected to the nearest grounding terminal. The unshielded part of the data cable must be as short as possible. •

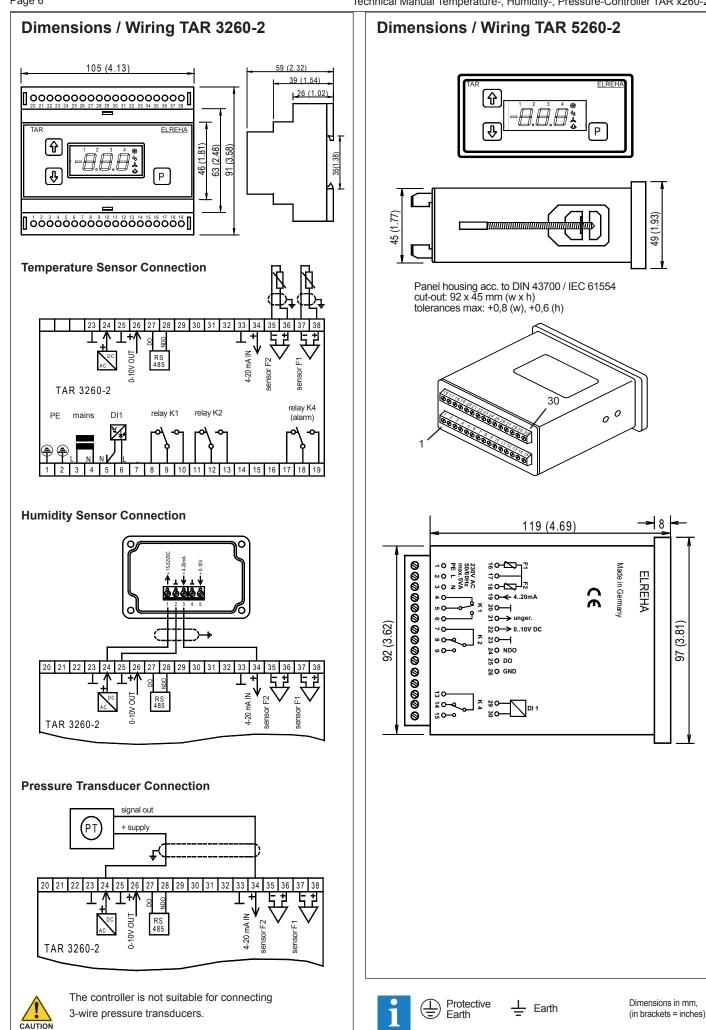
If networked controllers (**1260-2** types only) are supplied by one transformer only and the single positions must be switched off, use <u>double-pole</u> switches only. If not, the unit will be supplied partially over the shielding of the data connection and continues operation, depending on the secondary voltage of the transformer. Please note: If a unit is not supplied, the PC-software notifies a unit breakdown !

A better way is not to switch-off the supply voltage but to disable the unit by Digital Input.



Important: Never connect the secondary coil of the transformer to PE! Danger of destruction with networking!





#### Start-up Examples

#### **Dual Channel Temperature Controller**

#### Requirements:

Cooling ON at +10°C/ OFF at +9°C, Heating ON at +1°C/OFF at +2°C, the offset Heating/Cooling remains always equal, Overtemperture Alarm at +15°C, Undertemperature Alarm at 0°C, both after 30 minutes.

The alarm relay works active-low. At a certain time the setpoint must be increased by 2K (night operation). The controller works with the temperature sensor TF 201. The customer must be prevented from adjusting the setpoint lower than 0°C.

#### Please always note safety instructions!

If the TAR is switched ON, the display shows the value of sensor input 1.

1 Enter code number "70" at parameter P46

P26= 1, Sensor Type TF 201 and display in °C P14= 2, Operating mode with 1 control sensor (F1) only

Enter code number "88" at parameter P46

- P03= 9.0 (cooling setpoint, relay K1) P04= -7.0 (heating setpoint 7 K below P03, relay K2)
- P05= 2 (heating setpoint is relative value,
- coupled to the cooling setpoint) P06= 2.0 (cooling setpoint will be increased by 2K while night operation)
- P07= 1 (relay K1 will be activated with rising temperature)
- P08= 3 (relay K2 will be activated with falling temperature = Heating) P09= 1 (alarm relay K4 will be de-activated
- with an alarm)
- P10= 15 (the setpoint cannot adjusted higher than +15°)
- P11= 0 (the setpoint cannot adjusted lower than 0°)
- P12=1 (hysteresis of cooling relay, 1K) P13=1 (hysteresis of heating relay, 1K) P31=30 (alarm delay 30 minutes)
- P32= 5 (overtemperature alarm 5 K higher
- than cooling setpoint)
- P33= 0 (underemperature alarm at 0°
- P34= 1 (digital input open = night shift) P35= 0 (night shift works immediately)

Display Correction The Actual Value Display **P01** can be adjusted by P27, the Actual Value Display P02 can be adjusted by **P28**.

TAR as Humidity Controller

Requirements:

De-humidifying ON at 80% r.H., moisten ON at 60% r.H., hysteresis 2%, both setpoints are absolute values, no alarm, no night shift. The controller must work with the humidity transmitter FF 2520.

No setpoint limitation for the customer. The customer wants to read the humidity value on a remote display with 0-10V-input.

#### Please always note safety instructions!

If the TAR is switched ON, the display shows the value of sensor input 1.

- Enter code number "70" at parameter P46
- P26=5, Transmitters with 4-20 mA signal • P14=2, Operating mode with 1 control sensor only

Enter code number "88" at parameter P46 i

- P03=78.0 (de-humidify setpoint, relay K1) P04=62.0 (moisten setpoint, relay K2)
- P05=1 (setpoints are absolute values) .
- . P06=0 (no setpoint shift)
- P07= 1 (relay K1 will be activated by rising humidity = de-hum.) P08= 3 (relay K2 will be activated by falling
  - humidity = hum.)
  - P10= 100
  - P11=0

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- P12= 2 (hyst. for de-humidifying relay, 2%) P13= 2 (hysteresis for moistening relay, 2%)
- P29= 100 (display value with 20 mA current input)
- P30= 0 (display value with 4 mA current input)
- P34= 0 (Digital input disabled)
- P36= 100 (Analog output delivers 10V DC at 100% r.H.)
- P37= 0 (Analog output delivers 0V at 0% r.H.) P39= 1 (operating mode of analogue output)

Display Correction The actual value display P01 can be adjusted by P27.

If the measured values 'jump' check the following: Is the shielding of the sensor wire connected to PE near the controller unit? Is the PE terminal of the controller unit connected to PE? If the sensor wire is shielded correctly but the value on the display continues 'jumping', please try to solve the problem by removing the shield from PE and connecting it to a ground terminal of the TAR.

Installation hint:

Page 7

### **CONNECTION INFORMATION & SAFETY INSTRUCTIONS**



CAUTION

(UL)

The guarantee will lapse in case of damage caused by failure to comply with these operating instructions! We shall not be liable for any consequent loss! We do not accept liability for personal injury or damage to property caused by inadequate handling or non-observance of the safety instructions! The guarantee will lapse in such cases.

This manual contains additional safety instructions in the functional description. Please note them!

If you notice any damage, the product may <u>not</u> be connected to mains voltage! Danger of Life!

DANGER A riskless operation is impossible if:

- The device has visible damages or doesn't work
- After a long-time storage under unfavourable conditions
- The device is strongly draggled or wet
- After inadequate shipping conditions
- Never use this product in equipment or systems that are intended to be used under such circumstances that may affect human life. For applications requiring extremely high reliability, please contact the manufacturer first.
- The product may only be used for the applications described on page 1.
- Electrical installation and putting into service must be done from qualified personnel.
- During installation and wiring never work when the electricity is not cut-off ! Danger of electric shock!
- Never operate unit without housing. Danger of electric shock!
- All 'PE' terminals must be connected to ground. Danger of electric shock! Additionally, the internal noise filter will not work, faulty indicated values may occur.
- Please note the safety instructions and standards of your place of installation!
- · Before installation: Check the limits of the controller and
- the application (see tech. data). Check amongst others:
  Make sure that all wiring has been made in accordance
- with the wiring diagram in this manual.

file #.....E155131

- Supply voltage (is printed on the type label).
   Environmental limits for temperature/humidity.
- Maximum admitted current rate for the relays. Compare
- it with the peak start-up currents of the controlled loads (motors, heaters,etc.).

Outside these limits malfunction or damages may occur.

- Sensor/probe cables must be shielded. Don't install them in parallel to high-current cables. Shielding must be connected to PE at the end close to the controller. If not, inductive interferences may occur.
- Please note for elongation: The wire gauge is not critical, but should have 0,5mm<sup>2</sup> as a minimum.
- Mounting the controller close to power relays is unfavourable. Strong electro-magnetic interference, malfunction may occur!
- Take care that the wiring of interface lines meets the necessary requirements.
- All used temperature sensors must be identical. Never use different types at the same time. This will not work.
- TF-type sensors are not designed for being immersed in fluids permanently. In such a case, always use dip-fittings. With extreme temperature variations, the sensor may be damaged.

### Cleaning

The use of a dry, lint-free cloth and household agents is sufficient to clean the product.

Never use acids or acidic fluids! Risk of damage!



## Modifications of the -2 series

- Modified terminals and electrical connections

Error messages now available as codes + error listing
 Access codes can be entered at any parameter now.

- 3 new parameters added, code parameter is now P46

EC Declar	ation of Con	formity	CE		
For the devices TAR 1260-2, TAR 3260-2 and TAR 5260-2 we state the following: When operated in accordance with the technical manual, the criteria have been met that are outlined in the EMC Directive 2014/30/EC and the Low Voltage Directive 2014/35/EC. This declaration is valid for those products covered by the technical manual which itself is part of the declaration.					
Following standards were consulted for the conformity testing to meet EN 55011:2016, EN 61010-1:2010, EN 61326-1:2013 CE	t the requirements of marking of year: 20	•	uidelines:		
This statement is made for the manufacturer / importer	by:				
ELREHA Elektronische Regelungen GmbH D-68766 Hockenheim www.elreha.de	Werner Roeme Hockenheim	r, Technical Director	no Ci		
(Name / Address)	City	Date	✓ Signature		