Brief Description / Applications

The HMR controller was designed for transcritical refrigeration plants (e.g. Gas Cooler control CO₂). It can be used for High Pressure Control as well as for Receiver Medium Pressure Control.

- Designed for Gas Cooler Control (e.g. CO₂) in transcritical operation.
- The mode of operation can be set to High Pressure Control or Receiver Medium Pressure Control by setting just one parameter.
- The High Pressure Controller communicates with the Receiver Medium Pressure Controller by a dedicated interface to allow optimum modulation of the High Pressure Control.
- The High Pressure Controller is designed for motorized high pressure throttle valves, up to 120 bar.
- Receiver Medium Pressure Controller operates the gas bypass valve.
- Provides control based on COP characteristic.
- Equipped with intelligent support for heat recovery systems.
- Includes sophisticated protection functions to prevent loss of refrigerant.
- Provides probe-, pressure transducer- and digital inputs, relay outputs and analogue output as 0..10V or 4...20mA signal.



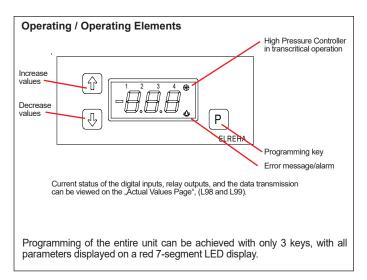


ELEKTRONISCHE REGELUNGEN GMBH

Technical Manual 5311437-04/03e/00 Gas Cooler Controller 2018-06-08, tkd/jr with parallel compression and heat recovery

From softw. vers. 1.18

HMR 3168 Type:



Programming

All the parameters of the HMR are organized in several parameter tables. The unit will display the following under normal operating conditions, when no key was pressed for at least 3 minutes:

1st priority......Current failure (blinking display).

2nd priority..........User selected ,permanent parameter to be displayed'.

Selecting and Changing Parameters

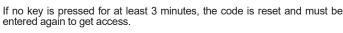
-	
Key	Action
P (> 2 sec.)	Page name will be displayed
û Ū	Select desired page
P	Enter the page
☆ ↓	Select parameter
P	Prepare programming. Enter access code if necessary
⇧ ⇩	.Change value.
	If you hold the key, the values change faster and faster
P	.Confirm programming
	Page name will be displayed again

Access Protection

Most parameters are protected and require a code to get access in order to change values. Perform the following steps to gain access to those parameters when needed:

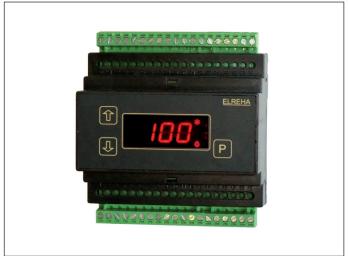


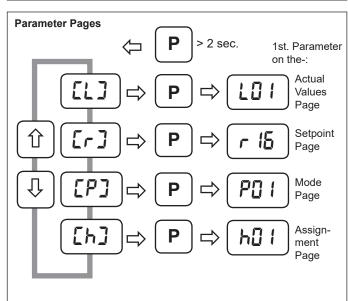
- 1. Press the "P" key to display the ,code entry' prompt.
- 2. Adjust the code to 88, using the "UP"/"DOWN" arrow keys.
- 3. Press the "P" key again to confirm.



Basic configuration of the controller for High Pressure or Receiver **Medium Pressure**

See page 3







Technical Data

	230V, 50-60Hz, max. 9VA (controller only)
	85% r.F., not condensing
Analogue Inputs	4x temperature sensors TF 201 (PTC)
or TF 50	01 (Pt 1000), as well as customer specific probes
1x press	ure transducer 0(2)-10V (scalable), Ri=69 kOhm
Measuring ranges	TF 501 (Pt1000)100°C+160°C
of the probe/temp. inputs	TF 201 (PTC, 2 kΩ at°C)50°C+100°C
	So140°C+25°C
	So250°C+50°C



Pay attention on the temperature ranges of probe heads and cables!

Accuracy	±0.5K in range -3525°C within
-	the ambient temperature range 1030°C
Digital Inputs	4x mains voltage, 3mA max.
	overvoltage category II, pollution degree 2
Relay Outputs	1x SPDT, 3x SPST, isolated, 8A res/3A ind./250V
•	overvoltage category III, pollution degree 2
SSR-Output (e.g. for EEx-V	/alve) 1x Solid-State-Relay (SSR),
	max. 0,5 A / 230VAC
	overvoltage category III pollution degree 2



Please note the information in the connection plan about a necessary snubber circuit at the SSR output!

Transducer Supply	22V DC ±10%, 40 mA max.
,	420 mA, max. shunt resistance 250 ohms
•	see parameter pages
	3x RS 485
Data storage	unlimited
Real Time Clock	automatic DST switch
	10 days clock backup without mains voltage
Housingplastic with	h foil keypad for rail mounting (DIN EN 50022),
	screw terminals 2,5 mm

Accessories

- Temperature probe TF 501, quantity depends on application
- Pressure transducer with 4-20 mA output
- PC-Software "CV-Scheduler"
- Module "COOLVision-MES" for remote control and configuration via VPR or SMZ systems.

CONNECTION INFORMATION & SAFETY INSTRUCTIONS



Product warranty does not cover damage caused by failure to comply with these operating instructions! Nor will ELREHA be held liable for any personal injury or damage to property caused by improper handling or failure to observe the safety instructions and recommendations contained in this or any other ELREHA supplied document related to this product! This manual contains additional safety instructions throughout the functional description. Please pay close attention to these instructions!



TO AVOID RISK TO HEALTH OR POSSIBLE LOSS OF LIFE, DO NOT OPERATE IF:

- The device has visible damage or doesn't work
- After a long storage period under unfavourable conditions
- · The device is heavily soiled or wet
- When shipped under inadequate conditions
- Never use this product in equipment or systems that are intended to be used in applications or under circumstances that may affect human life. For applications requiring extremely high reliability, please contact the manufacturer before use.
- This product may only be used in the applications described on page 1.
- Electrical installation and placement into service must be performed by qualified personnel only.
- To avoid the risk of Electrical Shock, all 'PE' terminals must be connected to ground. Without adequately grounding the unit, the internal noise filter will not work, which can cause faulty readings, or inaccurate displayed values to occur.
- Never operate the device without the supplied enclosure.
- To prevent electrical shock, the device may only be operated in a closed control cabinet or control box.
- Be sure to observe all local, state, or federal safety regulations in the location that the unit is installed.



- Before installation, verify that the control specifications suit the application details. Damage may occur if the unit is operated outside of its specified limitations.
 Examples:
- Supply voltage (printed on the type label).
- Environmental limits for temperature/humidity.
- Maximum current rating for the relays.
- Do not install sensor cables in parallel to high current cables. Shielding must be connected to PE at the end close to the controller. If not, inductive interferences may occur. The wire gauge should be no less than 0,5mm².
- Mounting the controller close to power relays is not recommended, due to the risk of strong electro-magnetic interference, which can cause the unit to malfunction!
- Ensure that the interface wiring meets all the necessary requirements.
- All used temperature sensors must be identical. Never use different types at the same time. This will not work.



Cleaning

The use of a dry, lint-free cloth is sufficient to clean the product. Never use liquids or acidic fluids! Risk of damage!

Basic Configuration High Pressure / **Receiver Medium Pressure**

- As the controller is switched on, press and hold the "X" key while "cFI" is displayed, then release
- Press the ,P' key when the display reads ,oFF'.
- When the C00 appears on the display, use the ,UP'/'Down' arrow keys to adjust the code to 88. Adjust the setting as needed. (0=Receiver Medium
- Pressure, 1=High Pressure).
 Once a selection is made, press the ,P' key to
- confirm the selection. All ,Setpoint Page' and ,Assignment Page' parameters will be reset to default settings simultaneously.

'Default Display Parameter' - Function

Once the controller is powered up, the display will show the selected ,default display parameter', unless there is a current failure, which will be displayed

*Note: The actual value of the pressure transmitter, (L15), is the factory preset.

To change the ,Default Display Parameter'

- 1. Select the parameter you want to be the
- Default Display Parameter'.
 2. Press the "û" and "∿" keys simultaneously.
 The display will then show ,888 momentarily before the new ,Default Display Parameter is displayed.

Error Messages / Error Memory / Error Codes

In the event of a failure, the controller will automatically display parameter ,L20' with a flashing abbreviation of the specific error, see error list below. If there is more than one error, the "UP"/"DOWN" keys can be used to scroll through the error list. The unit stores the last 15 error messages with date and time of occurrence. All the information is also available via data interface.

.....no error hַרַּםhardware failure PcoError parallel compressionHigh pressure lower alarm #FHHigh pressure upper alarm 5FLReceiver pressure lower alarm SEHReceiver pressure upper alarm Ł lbsensor 1 broken £26sensor 2 broken k3bsensor 3 broken k4bsensor 4 broken ٧եsensor 5 broken ŁБЬsensor 6 broken لا الدsensor 1 short-circuited £2csensor 2 short-circuited £3csensor 3 short-circuited בּץַבsensor 4 short-circuited £5csensor 5 short-circuited ŁБcsensor 6 short-circuited

5ELerror in assignment page, e.g. function selected too often

If a sensor is electrically shorted or broken, the alarm will be activated after a 5 second time delay.

A compound malfunction, reported by the VPR 5240-2, causes the blocking of the flashgas bypass

Parameter Pages

Actual Values Page [L]

Actual temperature value of sensor 1 (can be corrected ±10K, function see Assignment Page) Actual temperature value of sensor 4 Actual value of pressure transmitter, input 5 Actual value of HR offset, input 6 Actual error Actual value of gas cooler outlet HP averaged Actual value GCB outlet HP averaged Actual value of water outlet / shifting sensor GCB averaged Analogue output value to control the RMP valve, unlimited Analogue output value to control the RMP valve, current value If 0 V at DI → forced closure of the RMP valve, unlimited Analogue output value to control the HP valve, unlimited Analogue output value to control the HP valve, unlimited HP valve, 100% utilization forced by digital input signal HP valve, 0% utilization forced by digital input signal HR activated by digital input signal Receiver medium pressure actual value, from RMP control via master/slave (=no val.)	100,0+160,0 °C 1,0160,0 bar 1,0100,0 bar 0,0100,0 % 0,0100,0 % 0,1 0,1 100,0 % 0,1 100,0 % 0,1 100,0 %	
(can be corrected ±10K, function see Assignment Page) Actual temperature value of sensor 4 Actual value of pressure transmitter, input 5 Actual value of HR offset, input 6 Actual error Actual value of gas cooler outlet HP averaged Actual value GCB outlet HP averaged Actual value of water outlet / shifting sensor GCB averaged Analogue output value to control the RMP valve, unlimited Analogue output value to control the RMP valve, current value If 0 V at DI → forced closure of the RMP valve, unlimited Analogue output value to control the HP valve, unlimited Analogue output value to control the HP valve, unlimited HP valve, 100% utilization forced by digital input signal HP valve, 0% utilization forced by digital input signal HR activated by digital input signal	100,0+160,0 °C 1,0160,0 bar 1,0100,0 bar 0,0100,0 % 0,0100,0 % 0,1 0,1 100,0 % 0,1 100,0 % 0,1 100,0 %	
Actual temperature value of sensor 4	1,0160,0 bar 1,0100,0 bar	
Actual temperature value of sensor 4	1,0160,0 bar 1,0100,0 bar	
Actual value of pressure transmitter, input 5	1,0160,0 bar 1,0100,0 bar	
Actual value of HR offset, input 6		
Actual error		
Actual value of gas cooler outlet HP averaged		
Actual value of water outlet / shifting sensor GCB averaged		
Actual value of water outlet / shifting sensor GCB averaged		
Analogue output value to control the RMP valve, current value	0,0100,0 %0,1 0,0100,0 % 0,0100,0 % 0,1	
Analogue output value to control the RMP valve, current value	0, 1 0,0100,0 % 0,0100,0 % 0, 1	
	0, 1 0,0100,0 % 0,0100,0 % 0, 1	
	0,0100,0 % 0,0100,0 % 0, 1	
	0,0100,0 % 0, 1 0, 1	
HP valve, 100% utilization forced by digital input signal	0, 1 0, 1	
HP valve, 0% utilization forced by digital input signal	0, 1	L
HR activated by digital input signal		
	0.1	
Receiver medium pressure min. limit value, from RMP control via master/slave	' '	
Receiver medium pressure setpoint, from RMP control via master/slave		
Receiver medium pressure max. limit value, from RMP control via master/slave		
Operation mode	1 1	
operation mode	1 = transcritical	•
Status gas cooler bypass (GCB)		
	1 = GCB on	•
Parallel compression - Release status (0: locked, 1: released)		
, , ,	1 -	
		••
· · · · · · · · · · · · · · · · · · ·	I	
	-230V DI 1 2 3 4	
Status of the relays 1-5	ON — OFF	
	Status of RMP valve (0: locked, 1: released)	Parallel compression - on-delay remaining time

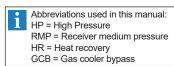
Parameters marked by "**Disp**" are for information only and cannot be changed.

Abbreviations used in this manual:
HP = High Pressure
RMP = Receiver medium pressure
HR = Heat recovery
GCB = Gas cooler bypass

Setpoint Page [r]

Param.	Disp	Note	Range	Factory Setting
r 15		Alarm delay RMP - upper	0900 sec	300
r 17	l	Alarm delay RMP - lower		
r 18		Delay time of redundancy relay RMP - Upper		
r 19	l	Delay time of redundancy relay RMP - Lower		
		Parallel compression - safety threshold high (relative to the setpoint medium pressure)		
		Parallel compression - switch off value (relative to the setpoint medium pressure)		
		Parallel compression - start value (utilization of the flashgas valve)		
		Parallel compression - start delay time		
-Du	1	Parallel compression - start delay time	0.600 sec	
		Parallel compression - stop delay time		
		Parallel compression - minimum down time		
r27		Parallel compression - error delay		
, _ ,	1	arailor compression - ener delay	300	
r30	ļ	Receiver medium pressure - minimum limit value	0,090,0 bar	30,0
r31	ļ	Receiver medium pressure - setpoint	0,090,0 bar	34,0
r32	ļ	Receiver medium pressure - maximum limit value	0,090,0 bar	38,0
r33	ļl	Receiver medium pressure - proportional range	0,120,0 bar	2,0
		Receiver medium pressure - integral time		
		Receiver medium pressure - factorization of the integral action		
		Receiver medium pressure - dead time compensation - step size		
		Receiver medium pressure - dead time compensation - interval time		
		Receiver medium pressure valve - maximum power limitation		
r40	ļl	High pressure - minimum limit value	0,090,0 bar	40,0
-41	x	Calculated high pressure setpoint, inclusive heat recovery offset		
		High pressure - maximum limit value		95.0
		High pressure - proportional range		
		High pressure - integral time		
		High pressure - factorization of the integral action		
		High pressure - dead time compensation - step size		
		High pressure - dead time compensation - interval time		
		High pressure valve - maximum power limitation		
		High pressure - setpoint for heat recovery		1
r50	ļļ	Offset from minimum limit (- ᢃ᠒) and maximum limit (- ᢃ᠒): HP modulation will start		
		when the RMP control's actual value touches the resulting threshold values	0,110,0 bar	2,5
r51	ļ	HP modulation factor: Influence to the HP setpoint while RMP deviation exceeds the limits	0,020,0 bar/bar	8,0
		defined by r50		
r52	ļ	Start utilization HP valve, if RMP is below the minimum value - 30	0,0100,0 %	10,0
		Latency period: minimum runtime for transcritical operation mode (above 76 bar)		
r54	ļ	Setpoint temperature limit latency range, below	10,030,0 °C	22,0
r55	ļl	Setpoint temperature limit latency range, above	10,030,0 °C	30,0
r55		Offset subcooling		
r57	<u> </u>	Alarm value HP, upper (relative to the calculated high pressure setpoint)	1,020,0 bar	2,0
r58	<u> </u>	Alarm delay HP, upper		
r59		Alarm delay HP, lower		
r60	<u> </u>	Delay redundancy relay HP, upper deviation	0300 sec	30
r5		Delay redundancy relay HP, lower deviation		
		GCB HP - proportional range		
r63		GCB HP - integral time		
, 64		GCB HP - factorization of the integral action		
		GCB HP dead time compensation - step size		
, 65 , 66		GCB HP dead time compensation - interval time		
, 60 , 67		GCB HP - OFF value		
		GCB ON delay after HP - OFF		,-
, 60 , 69				
- 70 - 70		GCB water temperature OFF value (relative value; r69-r70=ON value)		1 '
ァル ィフリ		HR offset by water outlet - temperature threshold high (absolute value)		
		, ,		1 '
		HR offset by water outlet - temperature threshold low (absolute value)		
ィ73 - 70		HR offset by water outlet - pressure offset high (relative value)		1
٠٦٢	† -	HR offset by water outlet - pressure offset low (relative value)	20,020,0 bar	0,0
r80		Digital input analogue value	0,0100,0 %	0.0
rou r90		Digital input analogue value		0,0
		Oil valve cycle time		2
		OII VAIVE OIN IIIIE	ひฮบบ ๖๕७	į J

Parameters marked by "Disp" are for information only and cannot be changed.

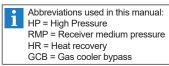


Mode Page [P]

Param.	Note	Range	Factory Setting
PO 1		0 1 2 3	1
P3 i	Actual value correction of sensor 1	+/-10 0 K adjustable	0.0 K
P32	Actual value correction of sensor 2	+/-10.0 K adjustable	0.0 K
733	Actual value correction of sensor 3	+/-10.0 K adiustable	0.0 K
774	Actual value correction of sensor 4	+/-10 0 K adiustable	00K
35	Actual value correction of input 5	+/-10.0 bar adjustable	0.0 bar
36	Actual value correction of input 6.	+/-10.0 bar adjustable	0.0 bar
סר	Davlight saving time (DST)	= variable	EU
71	Time zone offset		60 min.
בר	DST ON Month	(only for Eug) 1 12	3
73	DST ON Day DST ON x-Day	ໄໄonly for ະພຸດ) 0 (Sunday)6	0
74	DST ON x-Day	(only for ະພາດ) 05 (last). 0 = off	5
75		(only for ᢣᡎᠬ) 023`′′	2
75			10
77	I DST OFF Day	(only for ະພດ) 0 (Sunday) 6	0
8ר	DST OFF x-Day	(only for ະພາດ) 05 (last). 0 = off	5
79	DST OFF Hour	(only for Łun) 023	3
80	Year		
3 /	Month		
32	Dav		
33			
34			
35	Second		
37	Software version		
89			96(00)
90	Data transmission speed (baudrate)		

Assignment Page [h]

Param.	Note	Range	Factory Set
hD 1		. 0 = RMP, 1 = HP	1
hii	Function of relay 1	L, ρα= continuous on, RLR= alarm, Eρα= HP valve on,	RLR
	,	E _o F = HP valve off, P5P= release parallel compression passive,	
		P5R= release parallel compression active, b3P= gas cooler bypass ON,	
		a "L= pulsed output for oil return,	
		rEd= redundancy relay	
h 12	Function of relay 2	ditto	
h 13		l ditto	
ት ¹ ዛ		ditto	
h /5		ditto	
h20	Sensor type	. 501 (TF501/Pt1000), 201 (TF 201), S01, S02	501
_			
h21	Function of sensor 1	= switched off,	Łhd (HP)
		d 15 = display,	(SP)
		Ehd = gas cooler outflow temperature HP	
		b와 = gas cooler bypass sensor,	
		5hF = HR water outlet shifting probe HP	
		ditto	
		ditto	
		ditto	
<u>ኮ</u> ርኃ		= switched off,	con
. 76	F	= control input for HP resp. RMP	
hcb	Function of sensor 6 (voltage)	= switched off,	
		5hF = setpoint shift heat recovery	
LD /	Function of digital input (DI) 1	= switched off,	5-0 (UD)
na i		RnR = set analogue output to a fixed value	cor (NP)
		coP = receiver medium pressure input: flashgas bypass valve OFF	(3F)
		En = high pressure input: high pressure valve ON	
		EaR = high pressure input: high pressure valve OFF	
		rEc = high pressure input: HR (recovery)	
		PaP = lock parallel compression passive	
		PoR = lock parallel compression active	
		coR = receiver medium press. input: flashgas bypass valve OFF active	
		EoP = high pressure input: high pressure valve OFF passive	
		bpp = gascooler bypass request passive	
		bPR = gascooler bypass request active	
h32	Function of digital input (DI) 2	ditto	
h33	Function of digital input (DI) 3	ditto	
h34	Function of digital input (DI) 4	ditto	
hYO	Analogue output delivers	1 = voltage 0-10V, 0 = current 4-20mA	0
h4 !	Analogue output works as/delivers	= 0V / 4 mA	C00
****		100 = 100% (10V resp. 20 mA),	
		= receiver medium pressure / high pressure output	
		5EF = adjustable value in r80	
h93	Pressure transmitter lower limit input 5	1,0+160,0 bar	-1 0
h94	Pressure transmitter upper limit input 5	-1,0+160,0 bar	+60.0 (SP)
		.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	+160,0 (HP)
h95		Parameter display and failure monitoring only, if the digital input	.55,5 (111)
		function 'high pressure input HR' is selected	
		0,010,0 V	0.0
b95	Voltage high limit HR offset input 6	0,010,0 V	10.0
		. 0,010,0 1	
h97	HR offset lower limit input 6	. 0,0+100,0 bar	0.0
h98	HR offset upper limit input 6	0,0+100,0 bar	0.0
		1 - 7 7	,-



Real Time Clock

The built-in real time clock will run for a maximum of 10 days after mains power is lost.

To set Date and Time, use parameters "P80"..."P85" located on the "Mode Page".

Default time zone can be adjusted if needed, the factory preset is GMT+01:00, (,Time Zone Offset'=60 min.).

Daylight saving time switch - Time Zones

The unit is factory preset to automatically switch between DST and standard time based on the current EU-96 rules, (P70 = EU). This can be switched off or changed as needed.

Variable Time Zones

The function for Variable Time Zones can be activated using ,P70', and adjusted using ,P72'-'P79'.

P72 (DST ON Month) (Fact. Setting 3, March)
The month of the beginning of the
daylight saving time

P73 (DST ON Day)(Fact. Setting 0, sunday)
The weekday of the beginning of the
daylight saving time.

P74 (DST ON x-Day) (Fact. Set. 5, last sunday)
The x-th with "DST ON Day" preset day of the ...

P75 (DST ON Hour)..... (Fact. Setting 2, 2 o'clock)
The hour of the beginning of the
daylight saving time

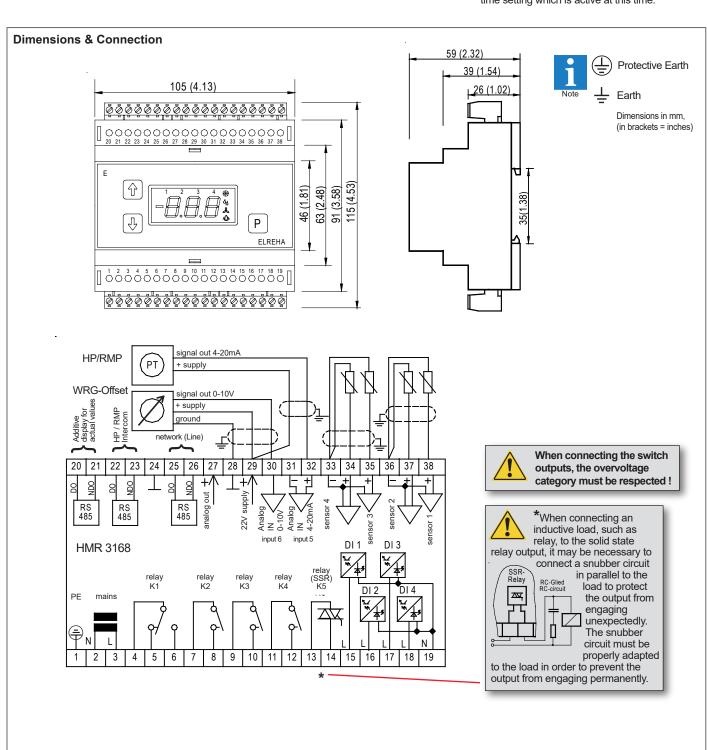
P76 (DST OFF Month)...(Fact. Setting 10, October)
The month of the end of the
daylight saving time

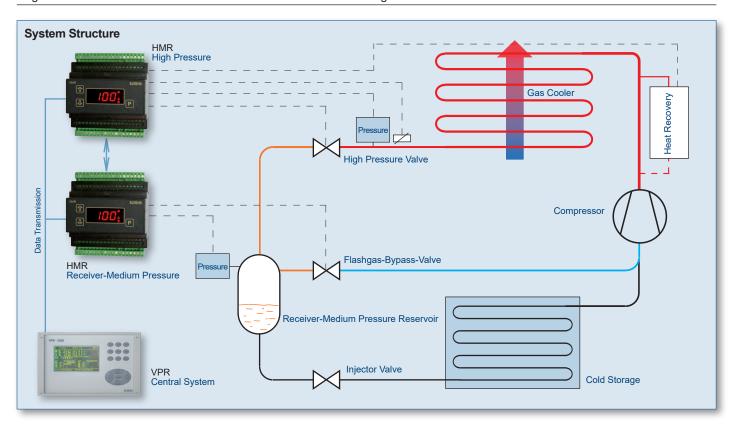
P77 (DST OFF Day)......(Fact. Setting 0, sunday)
The weekday of the end of the
daylight saving time

P78 (DST OFF x-Day) (Fact. Set. 5, last sunday)
The x-th with "DST OFF Day" preset day of the month

P79 (DST OFF Hour) (Fact. Set. 3, 3 o'clock) The hour of the end of the daylight saving time

The shift to DST resp. standard time is set by the time setting which is active at this time.





EC Declaration of Conformity ϵ For the device HMR 3168 we state the following: When operated in accordance with the technical manual, the criteria have been met that are outlined in the EMC Directive 2014/30/EC and the Low Voltage Directive 2014/35/EC. This declaration is valid for those products covered by the technical manual which itself is part of the declaration. Following standards were consulted for the conformity testing to meet the requirements of EMC and Low Voltage Guidelines: EN 55011:2016, EN 61010-1:2010, EN 61326-1:2013 CE marking of year: 2017 This statement is made for the manufacturer / importer ELREHA Elektronische Regelungen GmbH Werner Roemer, Technical Director D-68766 Hockenheim Hockenheim30.5.2017..... 00/ www.elreha.de (Name / Address) Date Signature

